



# SEMINARIO EJECUTIVO LATINOAMÉRICA

---

M I A M I **2019**

1st- 4th OCTOBER

# AUTOMATION. Creating value for the meat processing

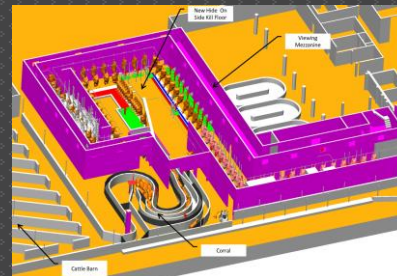


**Koorosh Khodabandehloo (KK)**



**BMC UK**

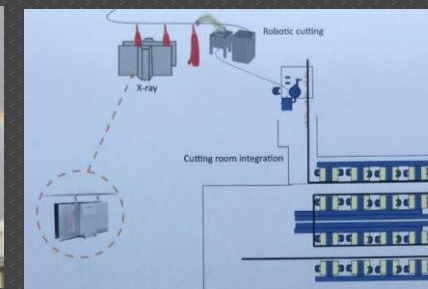
Adjunct Professor University of Southern Queensland Australia



**Beef**



**Lamb**



**Pork**



**EOL**

**Established  
1997**



**bmcdevon@aol.com**

# Koorosh Khodabandehloo



1979-82 Electrical Engineering Kings College, University of London

1982-85 Mechanical Engineering Imperial College, University of London

1985 Appointed at Univ. of Bristol

## University of Bristol

85-91 Lecturer

91-93 Reader – Director of AMARC

93-97 Prof. of Manufacturing Eng.

Dean of Engineering Research

Chairman AMIE Ltd

1997-to date

First development

Business and operations

Management of Change

Advice on new automation

Project management

## Interests

Robotics and automation in the processing of non-rigid products

## Sheet Material

*Fabrics composite materials*

## Bulk Material

*Meat, fish and poultry, dough products*

## Processes

*Cutting*

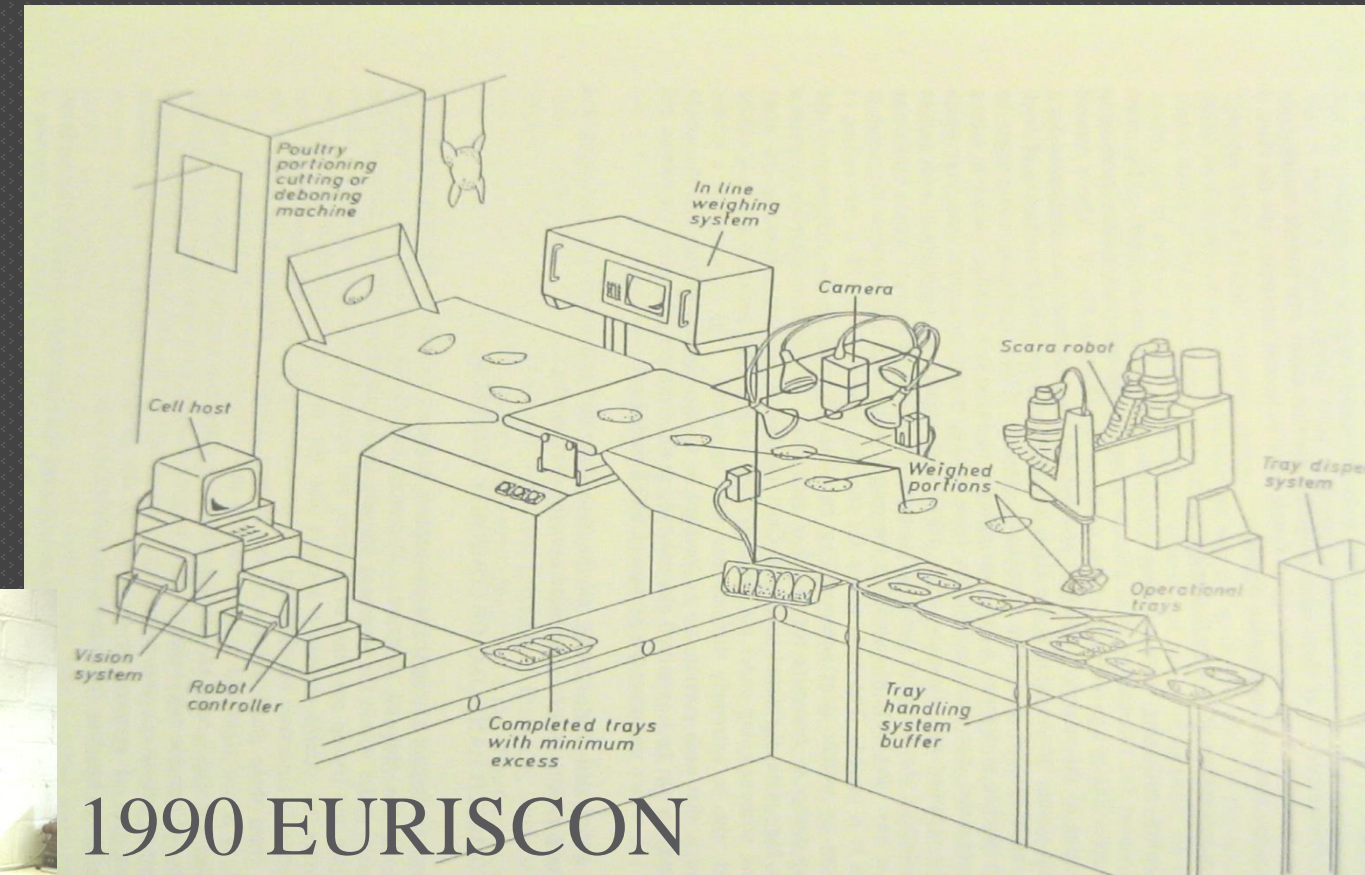
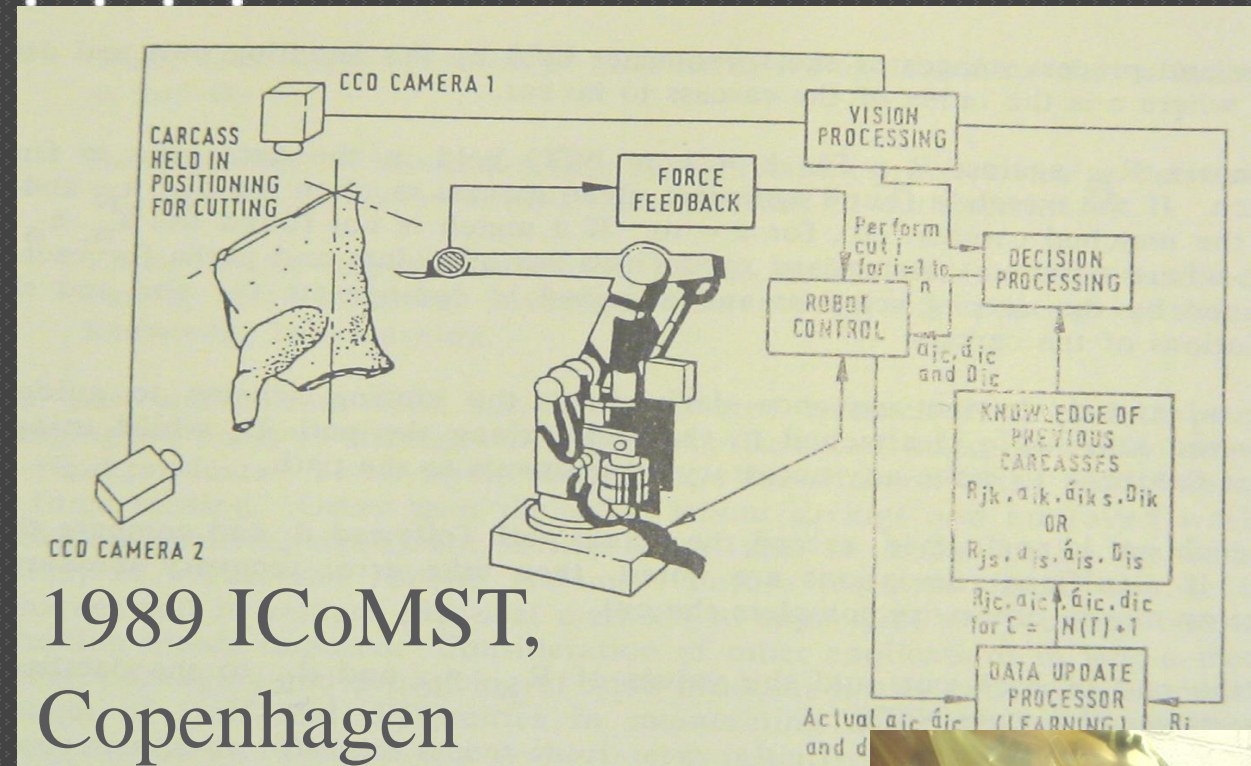
*Handling*

*Sensing including computer vision*

*Quality and total traceability*



# 30 years of meat robotics

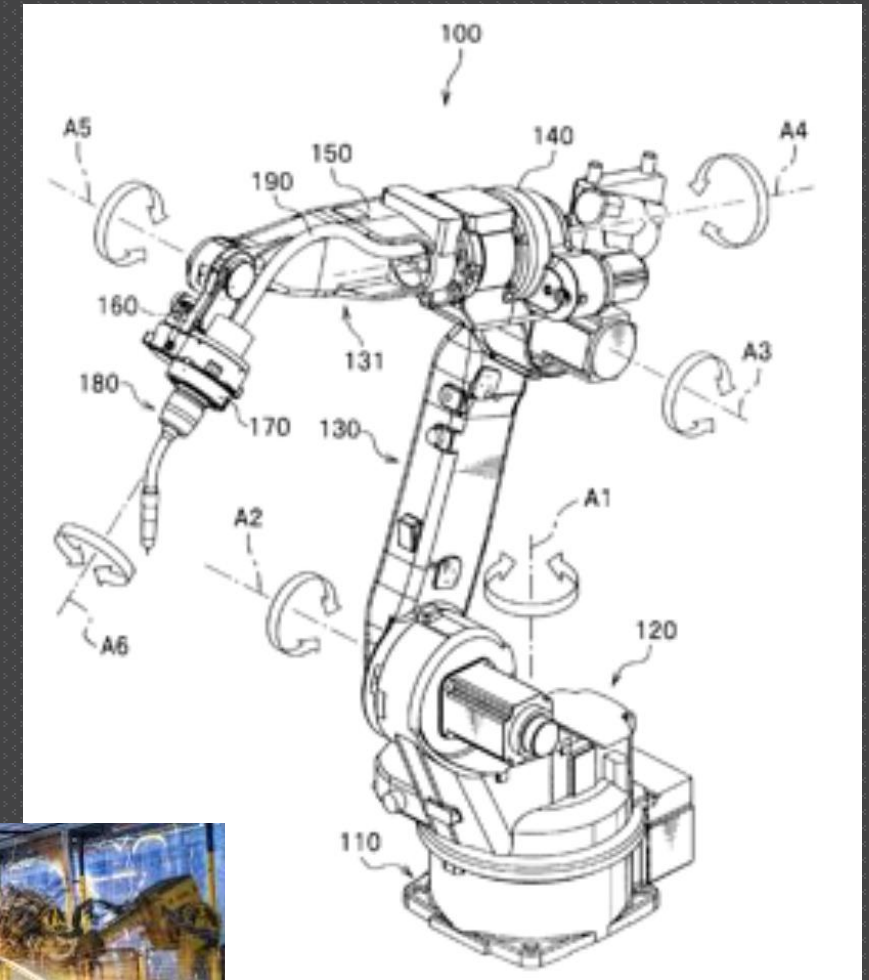
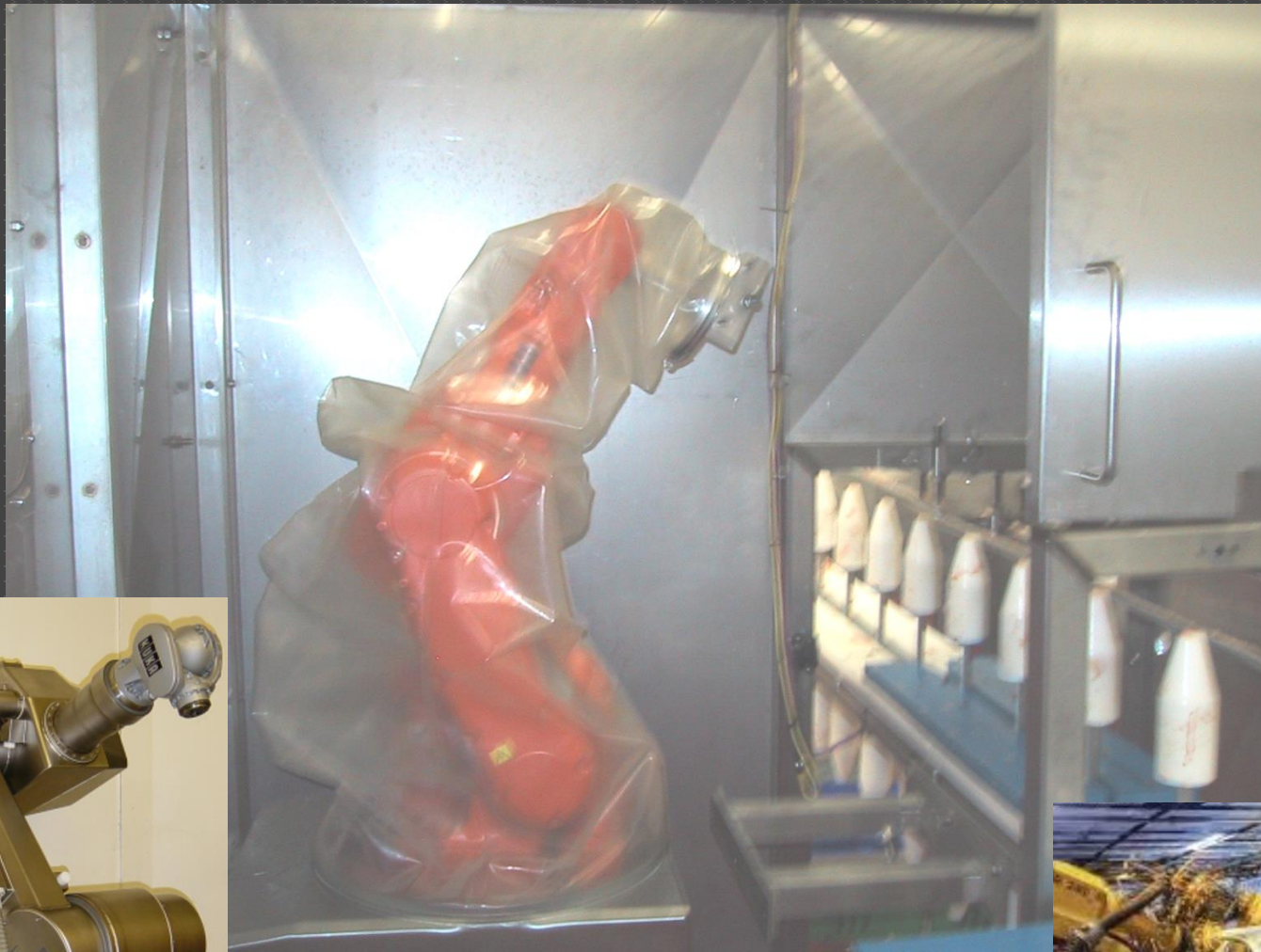




# Robotics for Meat Production

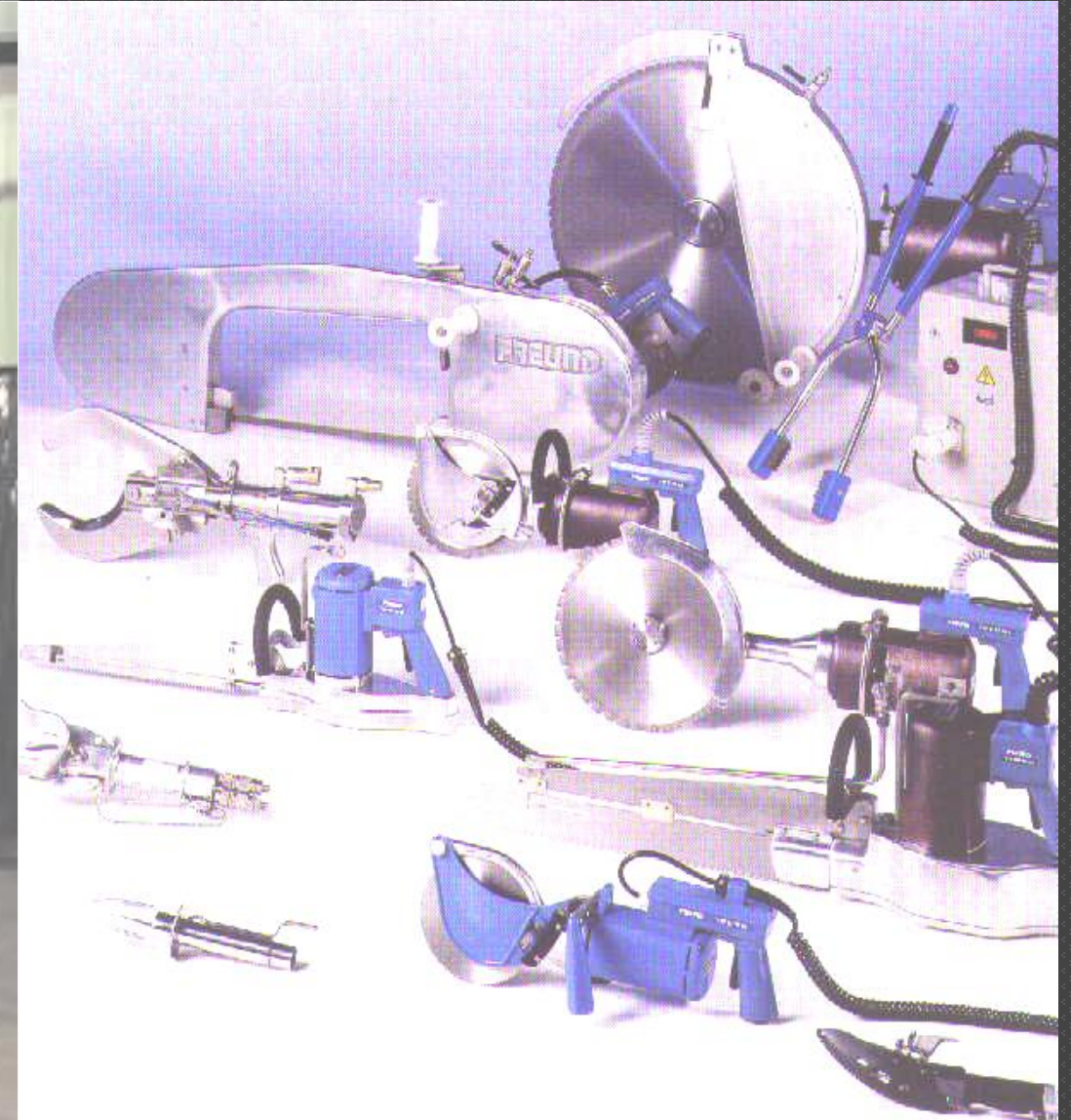


The basics have not changed





# Robotics for Meat Production



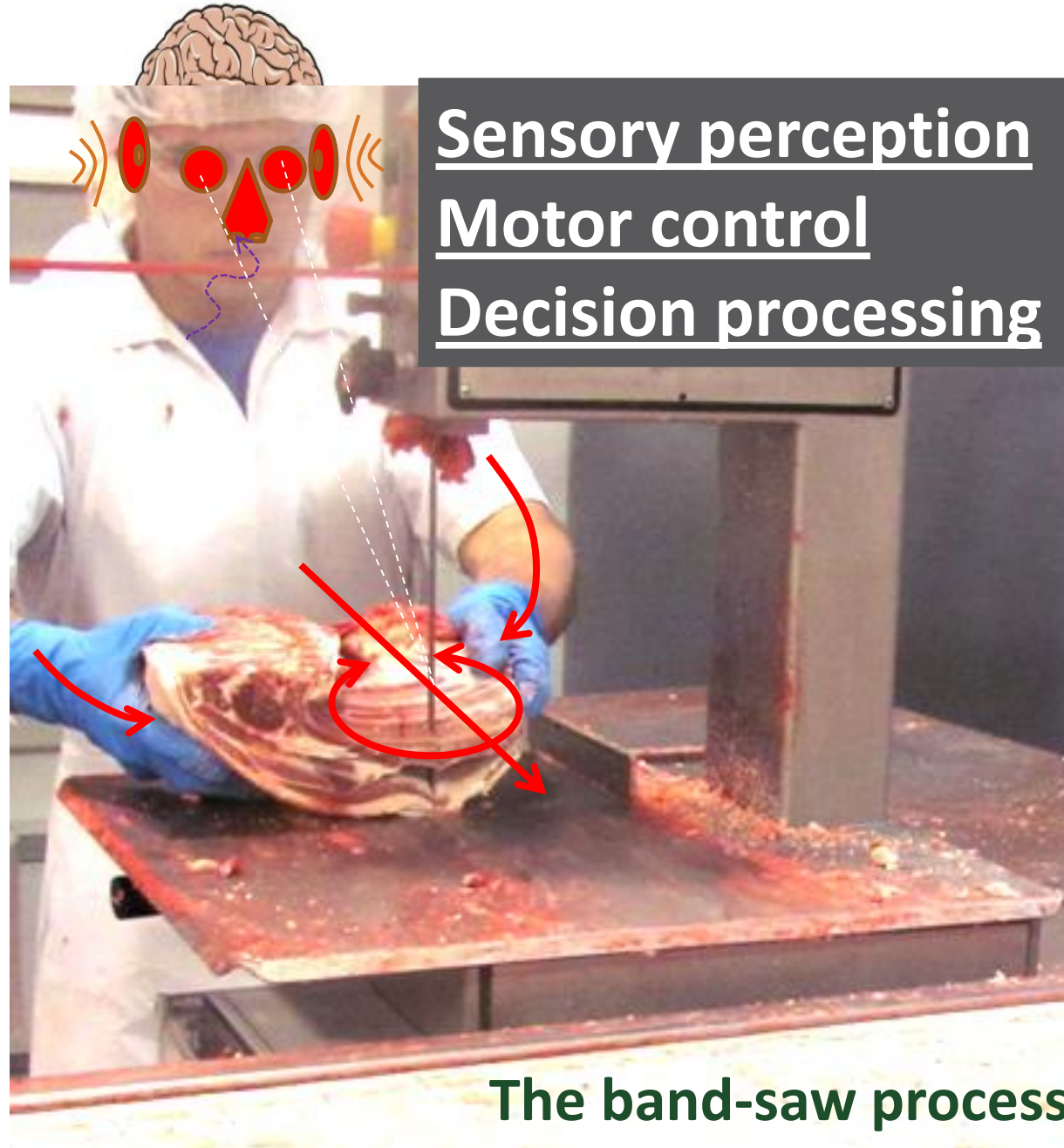


### Sensing capability:

- Vision
- Hearing
- Smell
- Force and torque

### Motion and manipulation control:

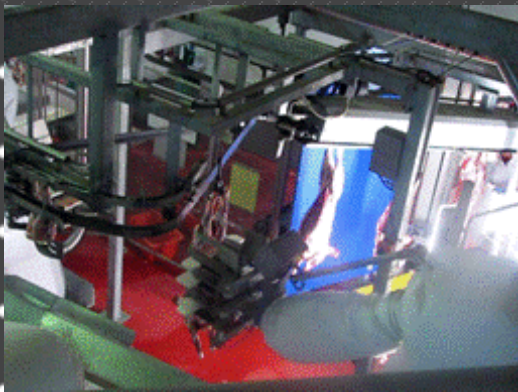
- attitude
- grip
- alignment
- feed rate
- applied force/torque
- path tracking



### Key motivating factors:

- Safety
- Quality and consistency
- Yield
- Operations cost
- Shortages of labour
- Training costs
- Other
  - Loss of productivity and efficiency
  - Operations Control
  - Electronic tracking
  - Agency and overheads costs
  - etc.

# Robot system developments and commercialisation



1986-1989

De-boning of beef (awaiting use in specific applications)

1987-1989

Packaging Poultry (specific solution available now)

1987-2000

Robotic handling of pre-preg (part commercialised)

→ 1988-2002

**Primal cutting of Pork (Commercialised)**

1989-2001

Fish processing (specific elements commercialised)

1989-1993

Slaughter line robots (now fully commercialised)

1991-1993

**Fixation of large non uniform products (commercialise)**

1991-1994

Non-rigid Material Modelling (Basic Research)

1992-1996

Handling, bagging and Packaging (elements commercialised)

1998-2001

Demonstration project for carcass breakup (commercialised)

1999-2002

Concerted Action (Meat Automation)

1997-2006

Processing sliced fish (awaiting commercialisation)

→ 1999-2001

**RoboPrint (Commercialised)**

→ 2001-2005

**RoboBurger (Commercialised)**

2003-2004

RoboProbe (in development)

→ 1999-2004

Robotic cutting of Poultry (pilot installed, awaiting)

→ 2006-2012

Robotic Ovine Cutting (Commercialised)

2004- on

Automating food production plants



# Robotics in pork operations

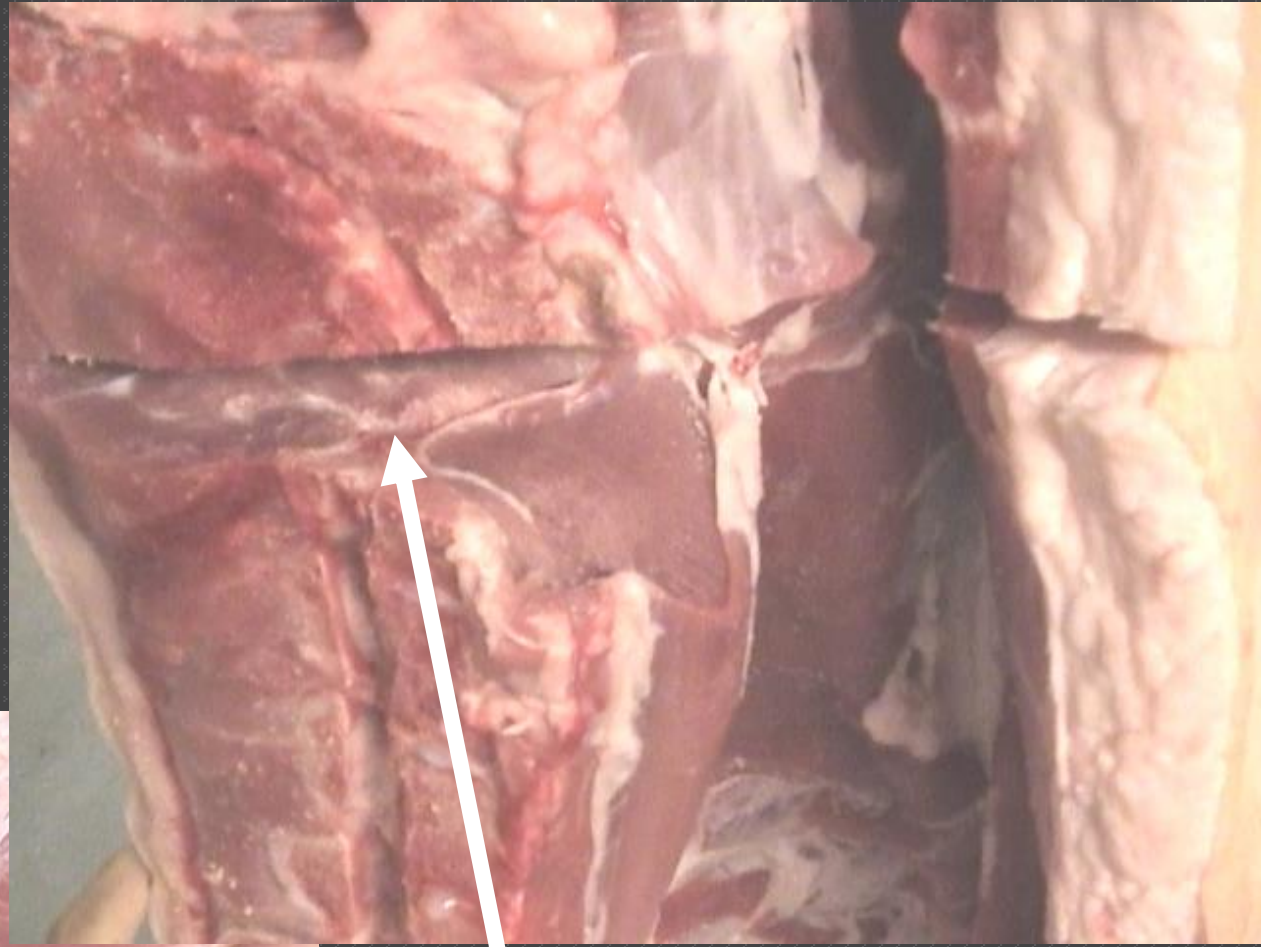


# Robotic Cutting





# Quality

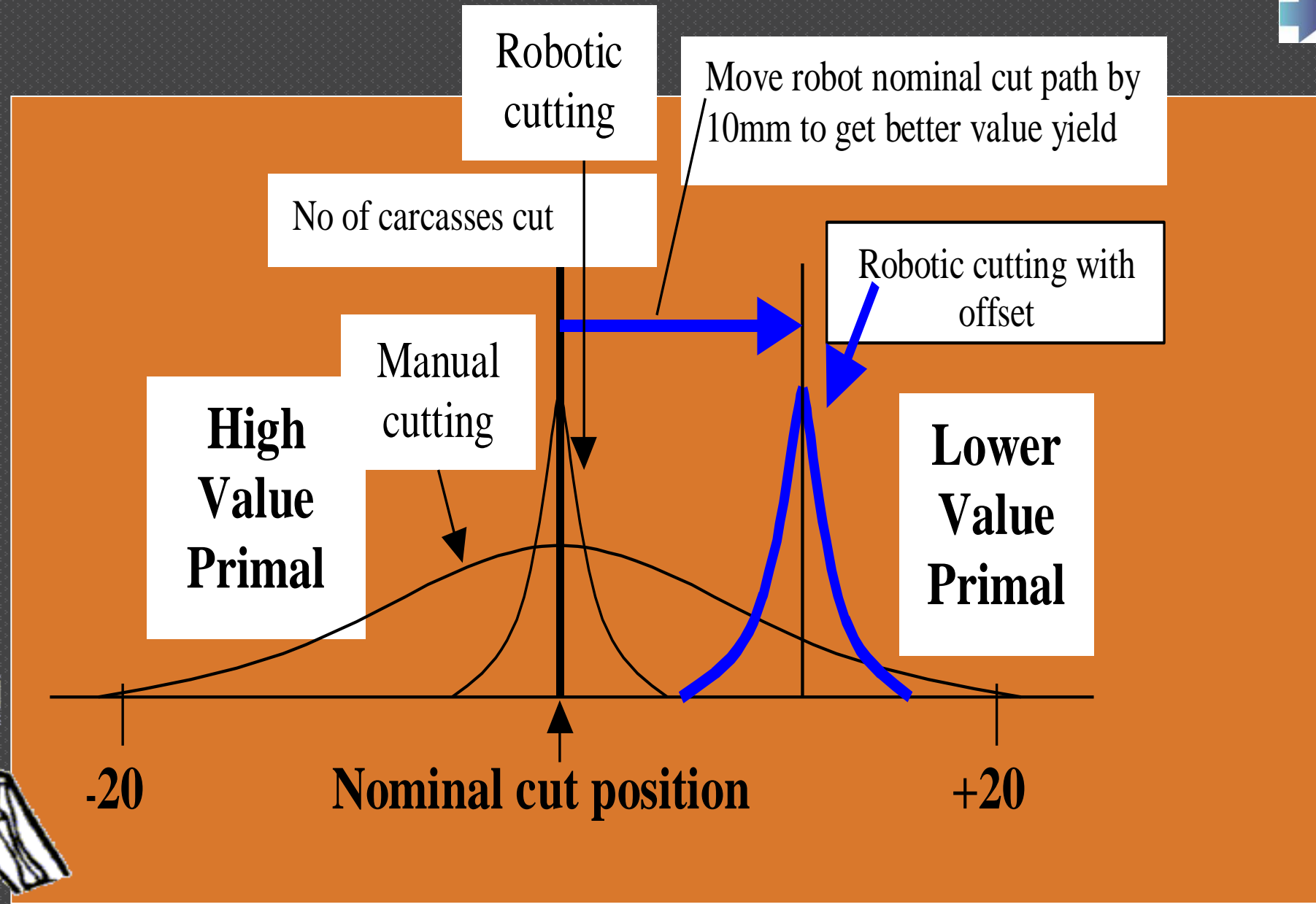
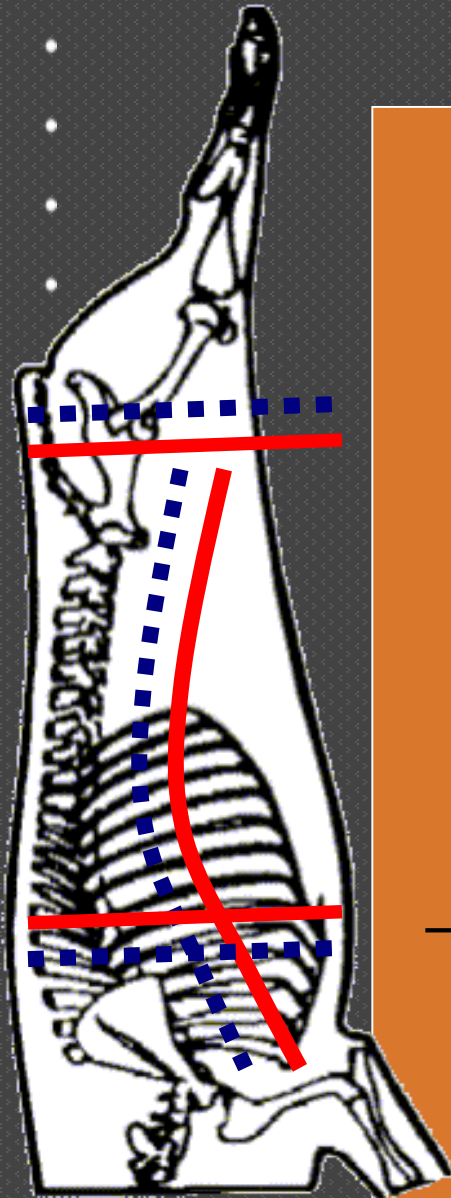


**No bone  
dust**



**Bone dust**

# Robotic Cutting - BENEFITS





# Robotic Cutting - BENEFITS



## Return on yield (Norway)

Controlling cuts at 113 head per hour,  
1720 hours/year.

B-L 1%-1.5% reported actual = 1,200,000 NOK  
3.5 X 132,000 US\$

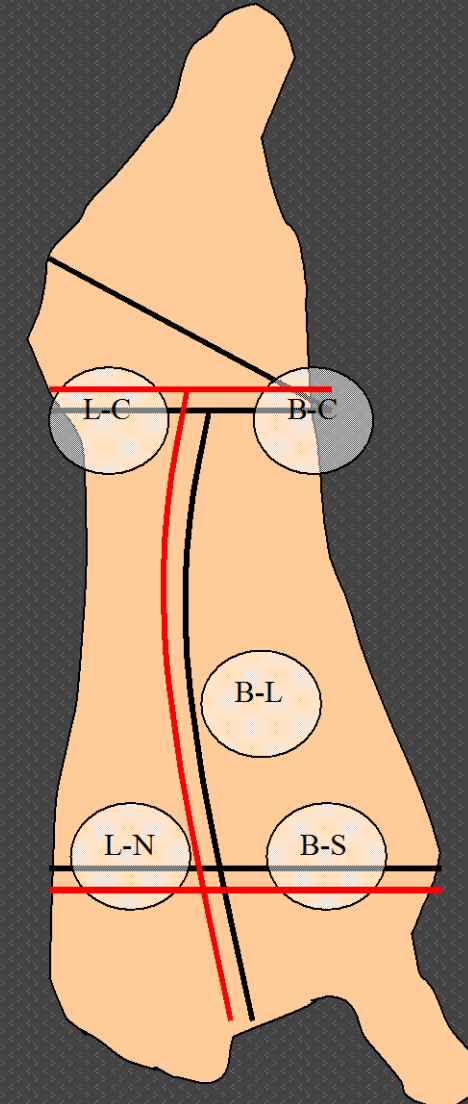
AT 600 PER HOUR this is ~5 X = 660k US\$/y

Belly-Loin	B-L	339,593	\$ 37k
Loin-Neck	L-N	703,218	\$ 77k
Belly-Shoulder	B-S	194,003	\$ 21k

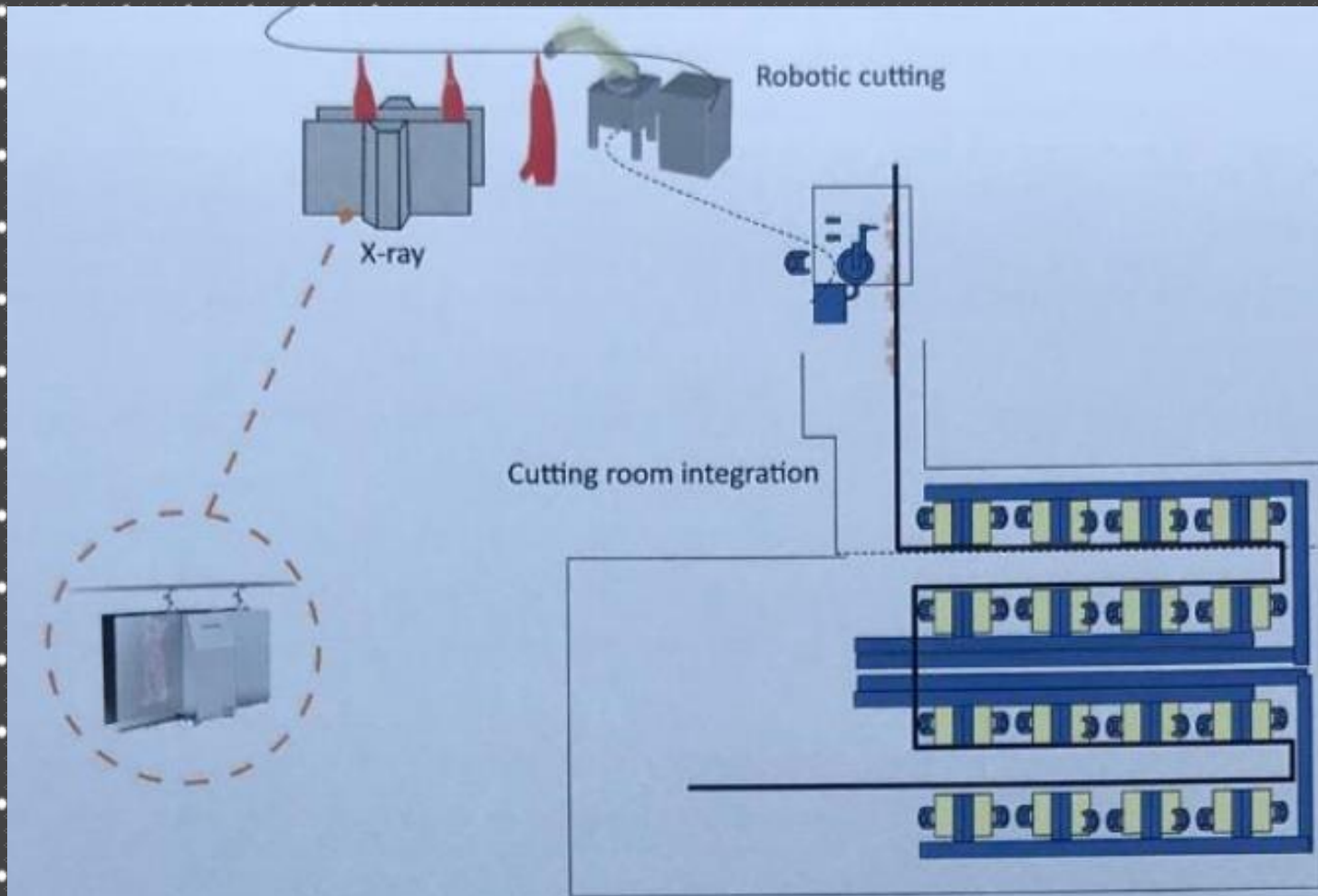
Total against 10mm offset		2,306,443	\$252k
------------------------------	--	-----------	--------

1 Norwegian Krone equals  
0.11 United  
States Dollar

1 Oct, 07:24 UTC · Disclaimer



# Pork cutting operation and opportunities



Gruppe 4:

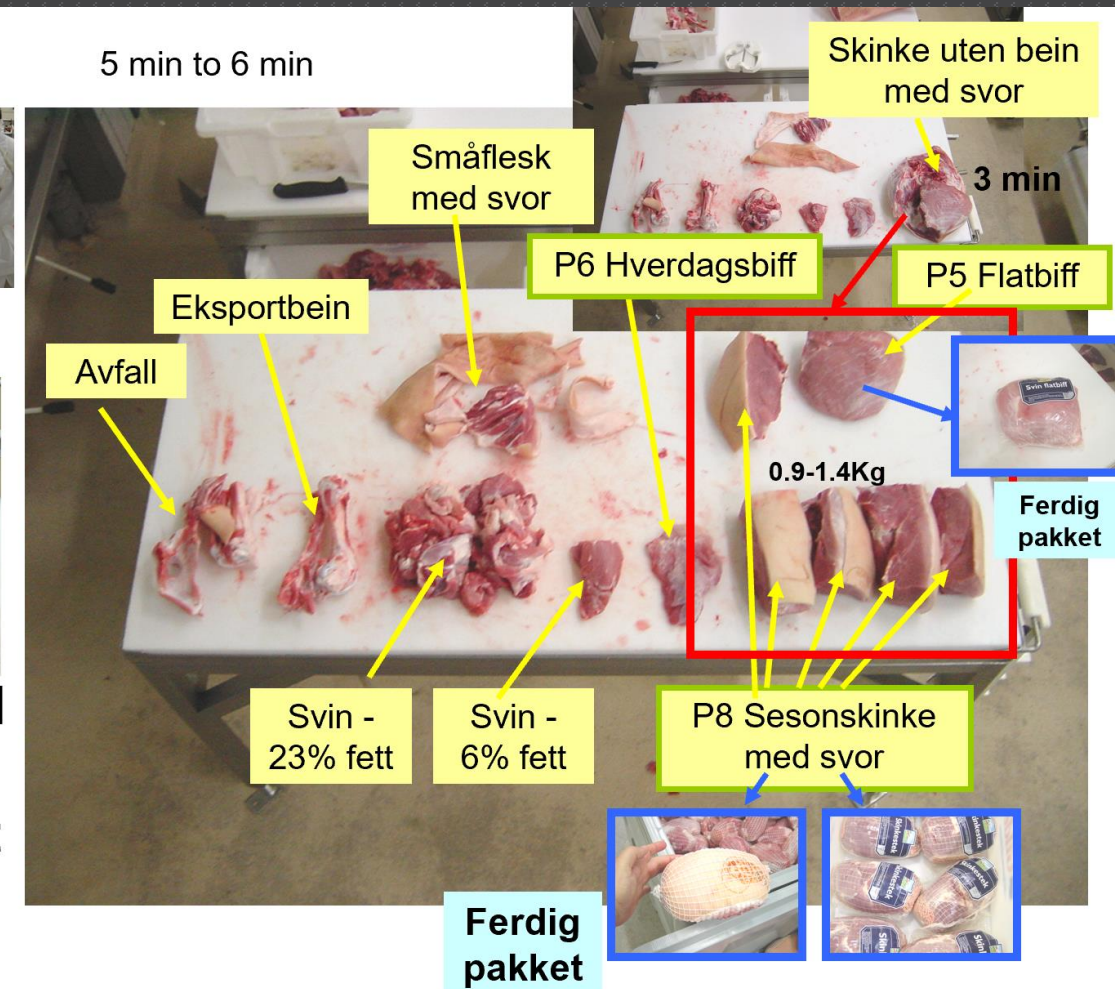
5 min to 6 min



Weight Control



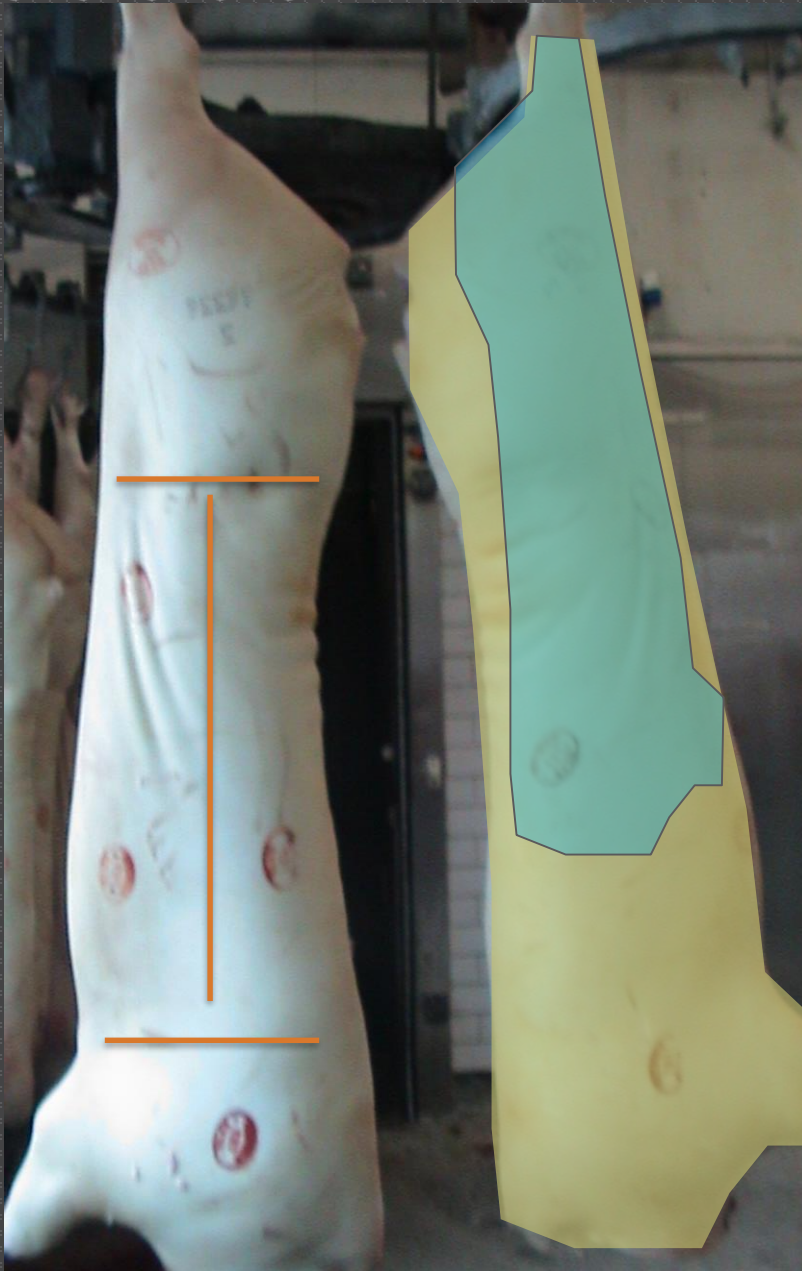
**Standard  
Skinke  
uten filet  
med  
mörbrad**



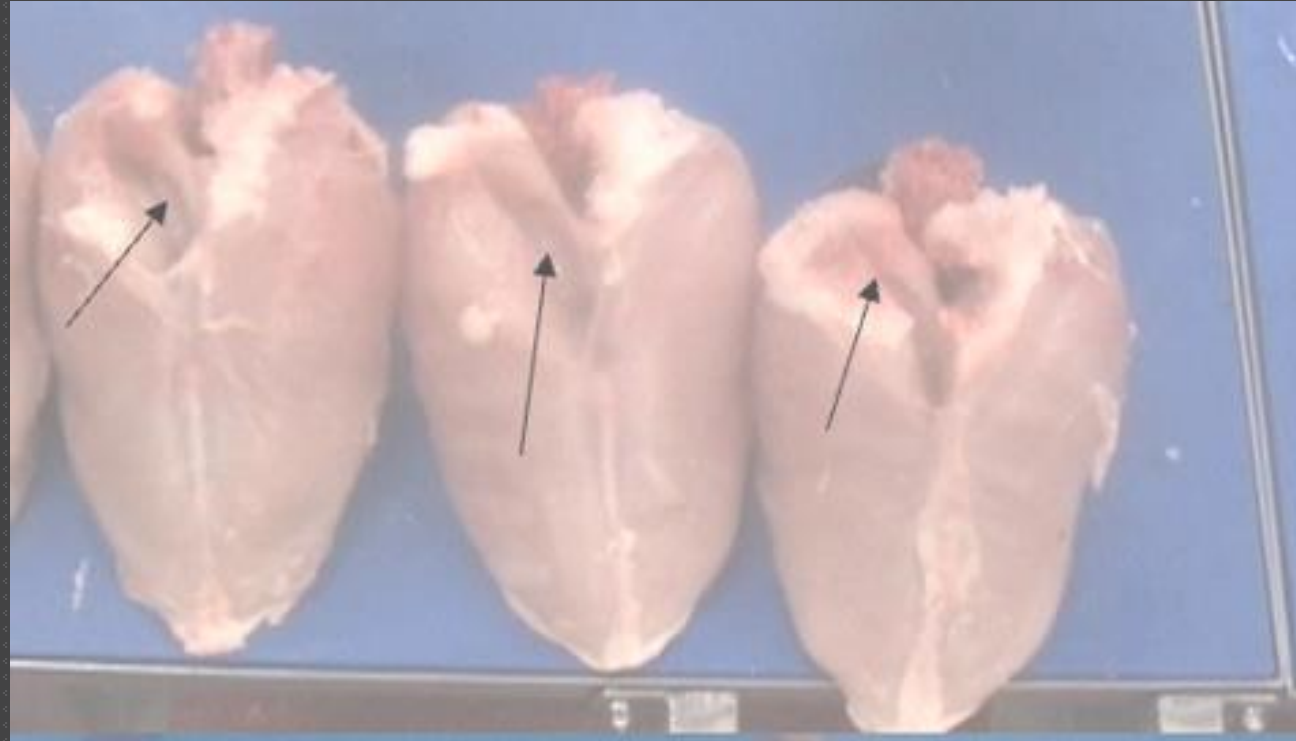
Control – yield – quality - other



# Robotic Printing



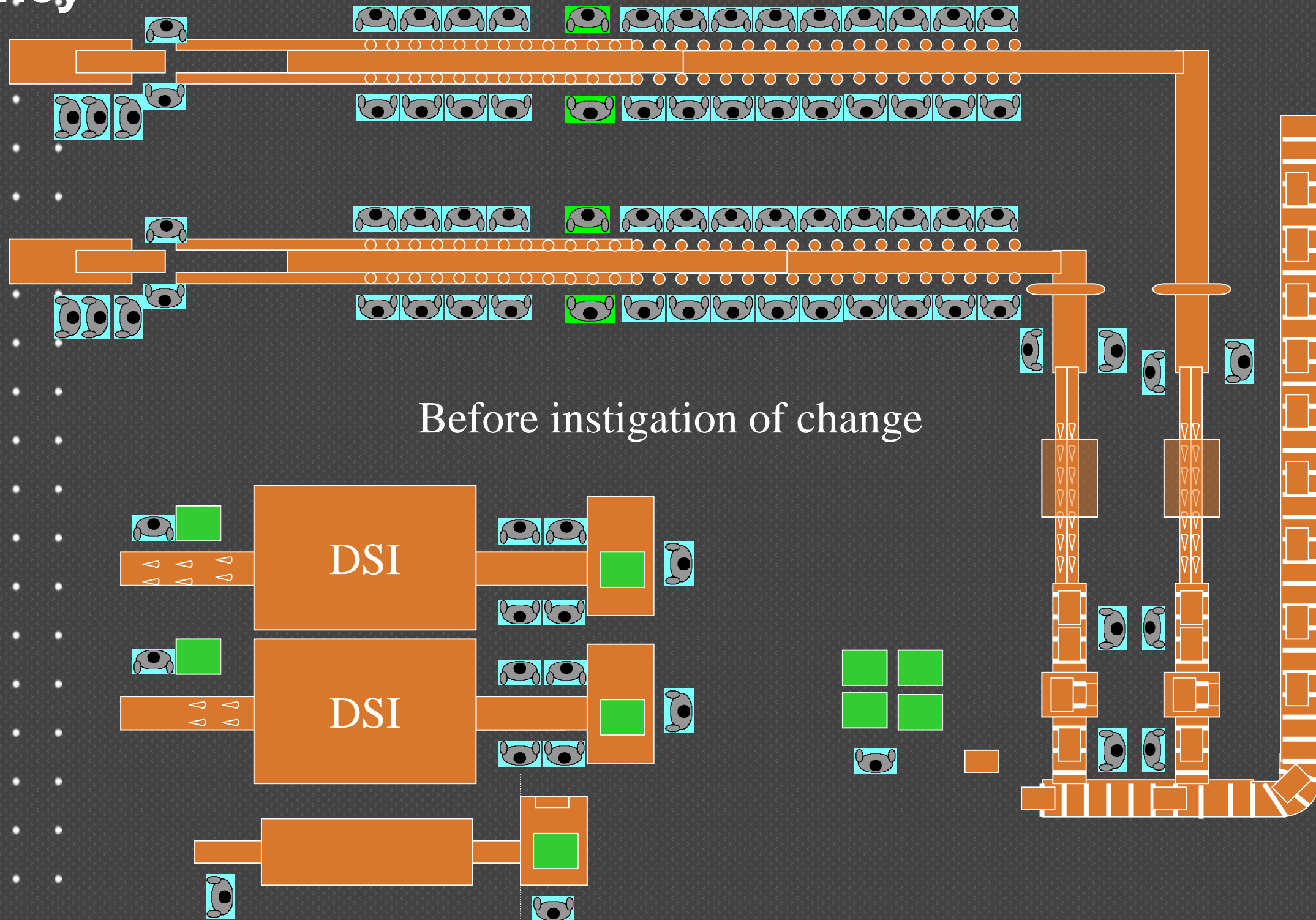
# Robotic Cutting - speed





# Efficiency

Not to scale



Not to scale

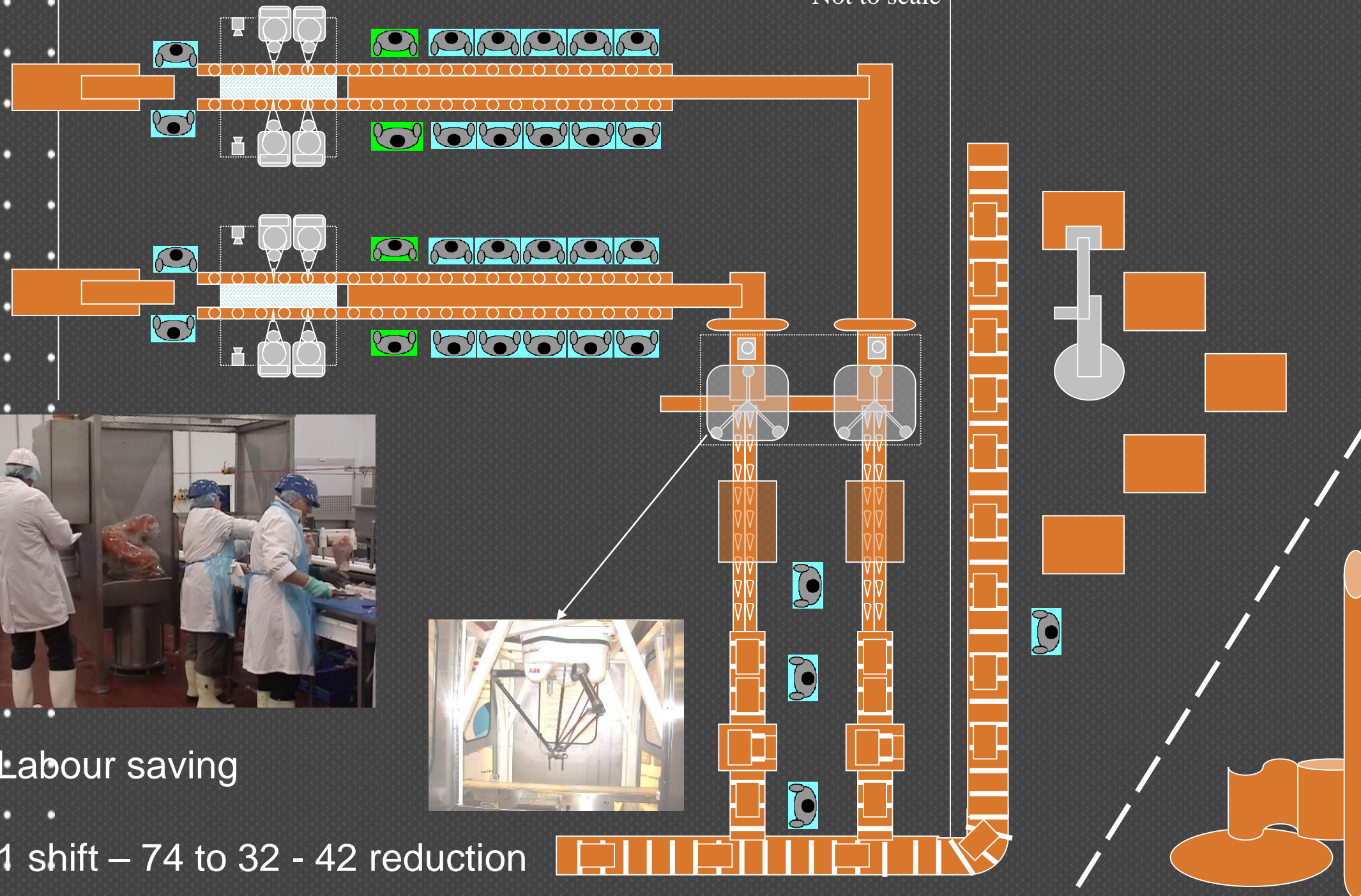


Labour saving

1 shift – 74 to 32 - 42 reduction



Project targets





# Robotic Cutting - speed



Hand cut



Robot Cuts



Hand cut



Hand cut



5%	
150	gs/fillet
7.5	g/fillet
32	birds/min
2	fillets/bird
60	mins/hour
29	Kg/hour
8	hours
230	Kgs/day
300	days/y
69,120	Kgs/y
2.10	\$/Kg
145,152	\$/year per line
4	lines
<b>581</b>	<b>k\$/year yiels</b>
6	people/line
20	k\$ /year person
<b>480</b>	<b>k&amp;/year labour</b>
<b>1,061</b>	<b>Tot/yer</b>



# Robotic Cutting





# Robotic Cutting



Calculation on loss and shift of x mm plus direct labour saving and effeciency increase					yields on 18.3 KG carcass		
	measured	weight in gs			AU\$	AU\$ loss on	AU\$
mm cut	25.00	equiv. to 1 mm	AU\$ Middle	AU\$	Diff/Kg	1mm bone dust	on 1mm shift
	307.00	12.28	6.00	5.00	1.00	0.061	0.012
	328.40	13.14					
hour R	600						
on 1mm	60						
	5						
x at Rate R/hour AU\$	155						
	7.50						
	2						
	5						
	50						
	3,750						
duced loss/year	226,818	AU\$					
x mm/year	581,490	AU\$					
ss and 5mm shift	808,308						
	3						
	50,000.00						
ing per shift	150,000.00						
n S shift	300,000.00						
in boning and packing area	54.00						
urrent	8.50	per minute					
fter robot	10						
ghput % with no staff increase	18%						
fit in labour equivalent on single shift	10	people					
S shifts	952,941	AU\$					
Total gain estimate	2,061,249						
Price	1,870,000						
ROI	11						



# Robotic Cutting



E+V VRSS 2000 - EV1

File Edit Macro View IO-Port Robot Scale Extras Window ?

**Results**

Status	Camera 0	Camera 1
Action	Finished	Finished
Time	0.000000 s	0.000000 s
Evaluation	Finished	Finished
Time	0.122834 s	0.000000 s

Estimated Value  
Carcass  
Date-Time  
Buffer

**Cut Settings**

☒ Leg Cut  
☐ Middle Cut  
☐ Partial Cut  
☒ Shoulder Cut

Offsets:

Leg Cut: 0  
Middle Cut: 0  
Depth partial Cut: 0  
Shoulder Cut: 0

OK  
Abbrechen

Back  
0  
008 07:30:03  
0

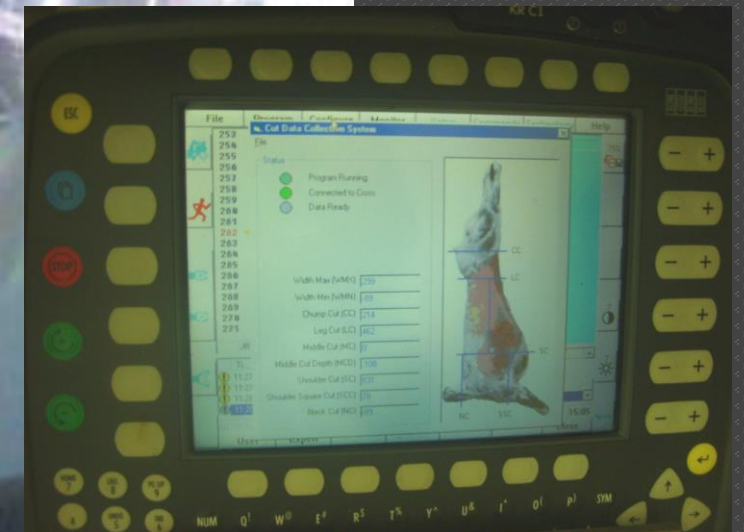
03.04.2008 07:32:47: L:1110, LC:492, MC:663, SC:895, DMC:112  
03.04.2008 07:32:44: Camera 0: Image C:\e+v\Projektdaten\VRSS\2008\Images\marked\S  
03.04.2008 07:32:37: L:1118, LC:496, MC:668, SC:901, DMC:108  
03.04.2008 07:32:33: Camera 0: Image C:\e+v\Projektdaten\VRSS\2008\Images\marked\S

**Camera 0**

A 3D model of a pig carcass, viewed from the side, overlaid with a green grid. The model is positioned within a blue rectangular frame. The grid lines are colored green, yellow, and red, and the carcass itself is rendered in a realistic, slightly translucent skin texture.



# Robotic Cutting

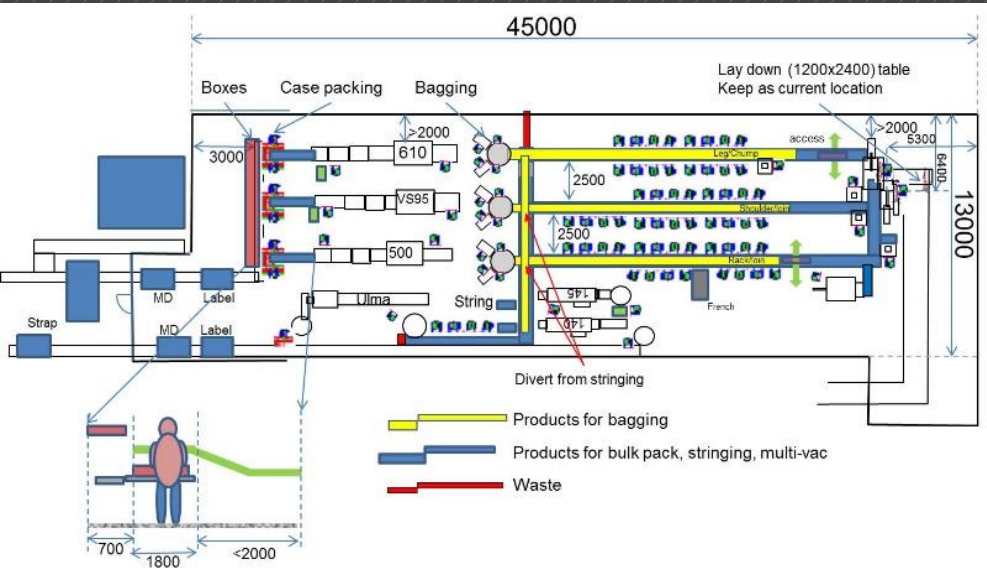
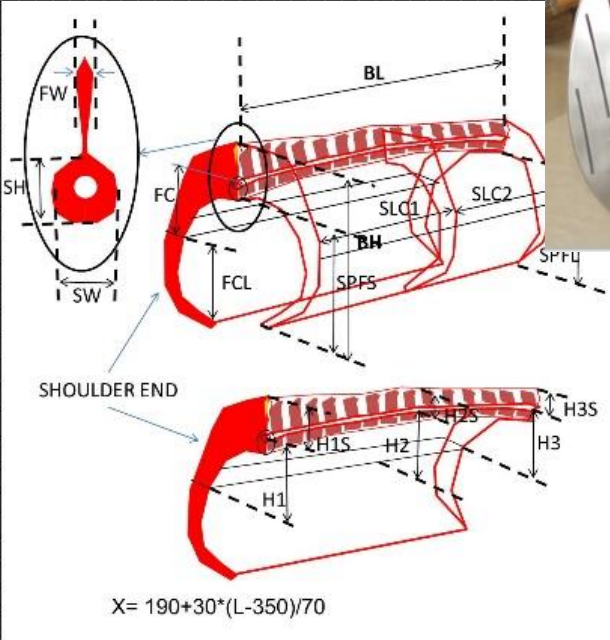




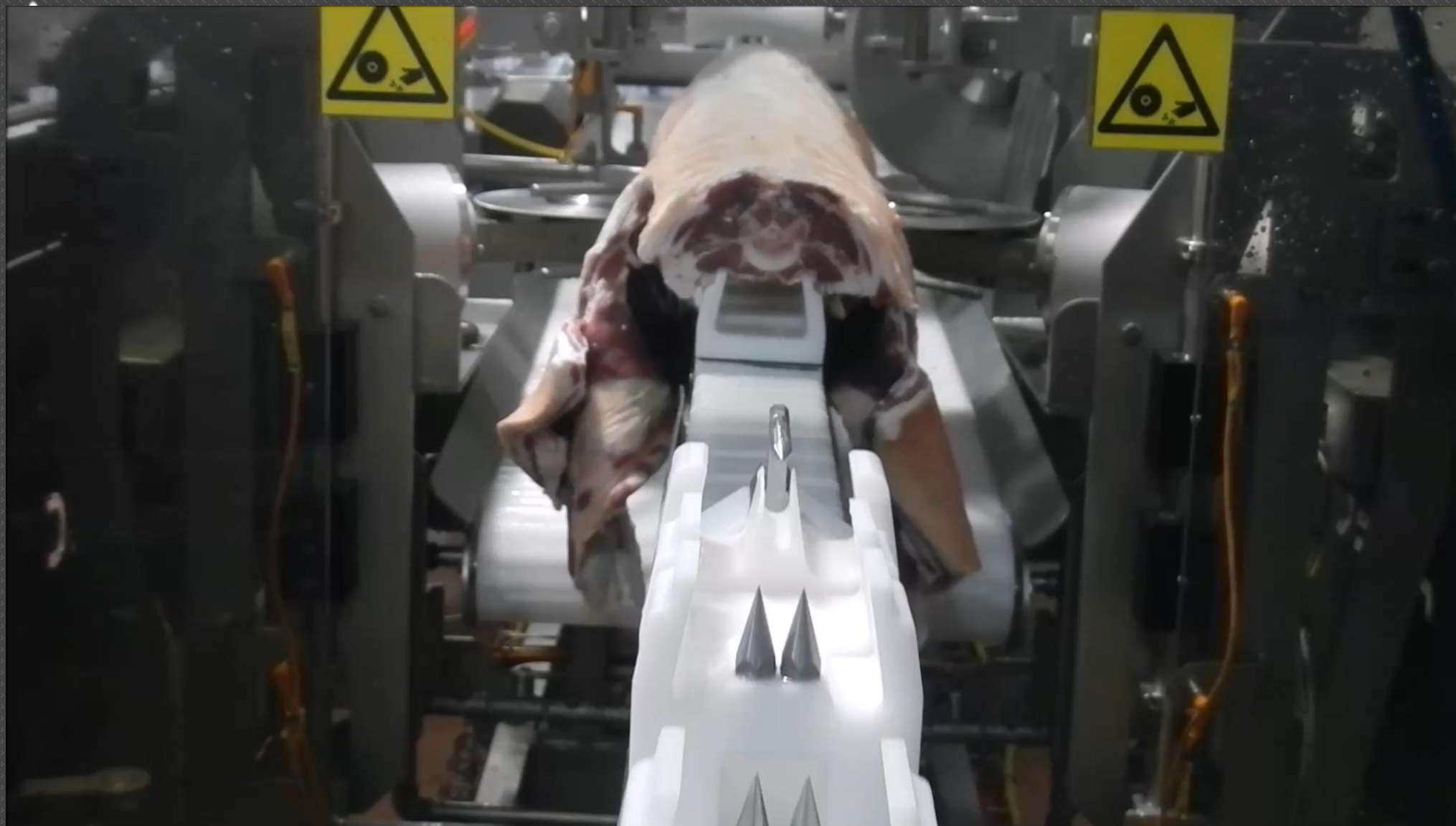
# Lamb solutions



June WBM		mm
Measurements Oct 2012		
	Carcass A	Carcass B
Kg	13.9	32.2
Lngh	900	1180
Wdth	200	280
Barrel measurements		
Carc	A	B
BL	350	420
BH	240	340
SLC1	190	220
SLC2	160	200
SW	35	45
SH	35	46
FW	8	13
FC	60	60
H1	30	20
H2	40	40
H3	30	20
H1S	80	110
H2S	50	65
H3S	60	85
SPFS	145	230
SPFL	140	100
FCL	90	190







Calculation on loss and shift of x mm plus direct labour saving and efficiency increase				yields on 18.3 KG carcass		
	measured	weight in gs		AU\$	AU\$ loss on	AU\$ diff
mm cut	25.00	equiv. to 1 mm	AU\$ Middle	AU\$	Diff/Kg	
Leg/middle	307.00	12.28	6.00	5.00	1.00	
Shoulder/middle	328.40	13.14	6.00	3.00	3.00	
Carcasses per hour R	600		Per carcass total	AU\$		
Loss/hour AU\$ on 1mm	60					
mm Shift x	5					
Gain on shift of x at Rate R/hour AU\$	155					
hours/shift	7.50					
Shifts S	2					
Days per week	5					
Weeks/year	50					
Total hours	3,750					
Gain on 1 mm reduced loss/year	226,818	AU\$	note using lower value primal price			
Gain on shift of x mm/year	581,490	AU\$	using difference in price			
Gain with no loss and 5mm shift	808,308					
Labour per shift	3					
Cost	50,000.00					
Total labour saving per shift	150,000.00					
Labour saving on S shift	300,000.00					
Number of staff in boning and packing area	54.00					
Rate of lambs current	8.50	per minute				
Rate of lambs after robot	10					
Increased throughput % with no staff increase	18%					
Increased benefit in labour equivalent on single shift	10	people				
AU\$ benefit on S shifts	952,941	AU\$				
Total gain estimate	2,061,249					
Price	1,870,000					
ROI	11		-			



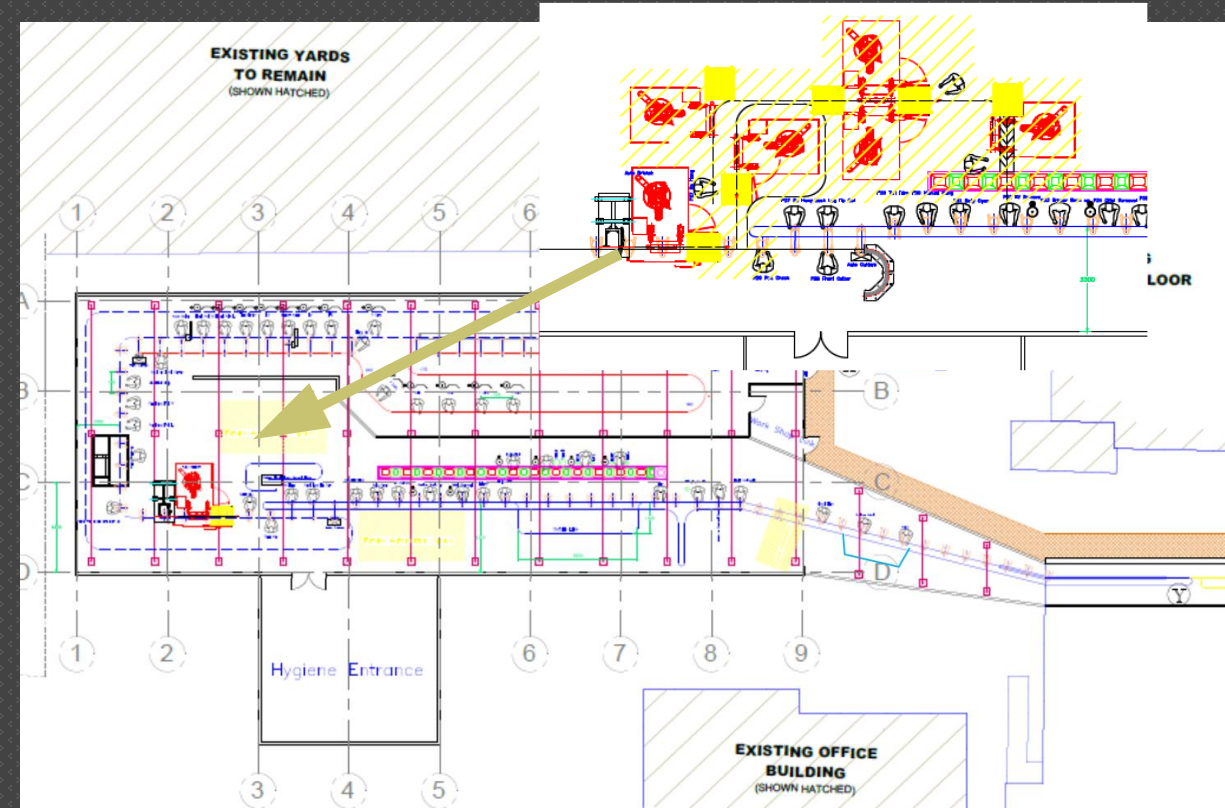
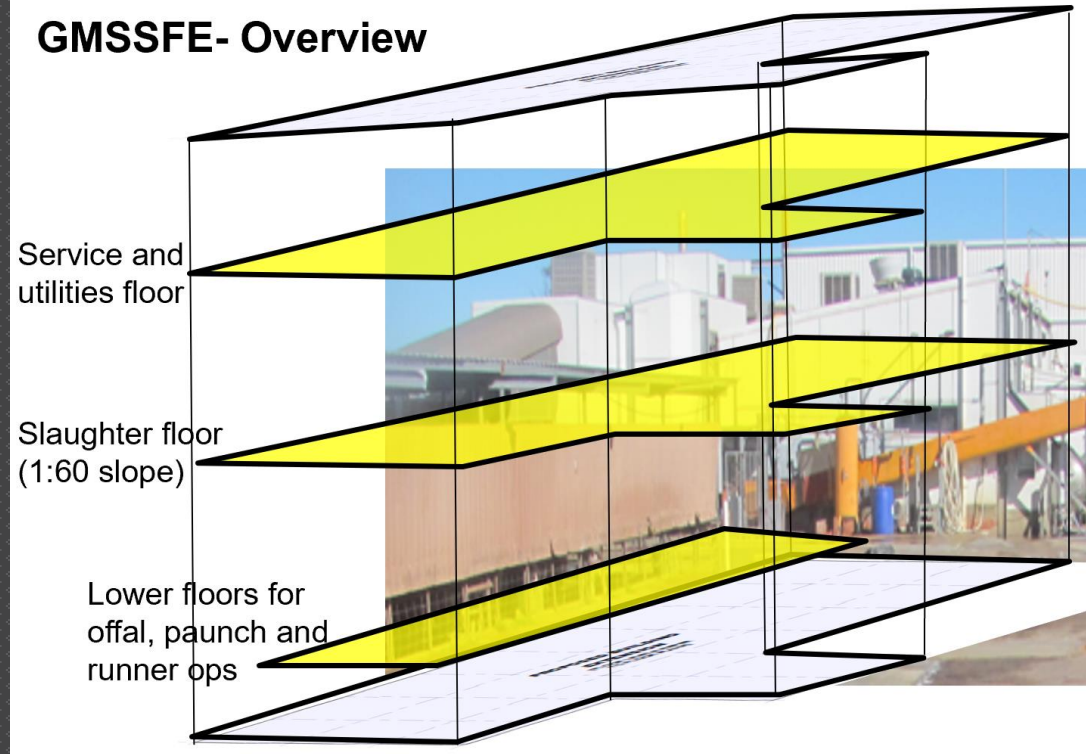
US\$ 1.4m



# Lamb solutions



## GMSSFE- Overview



In memory of Barry Noble



# Beef cutting



Shelf life extension



E+V Technology, Germany



Cutting line consistency and accuracy



# End of line

## 1. Packing

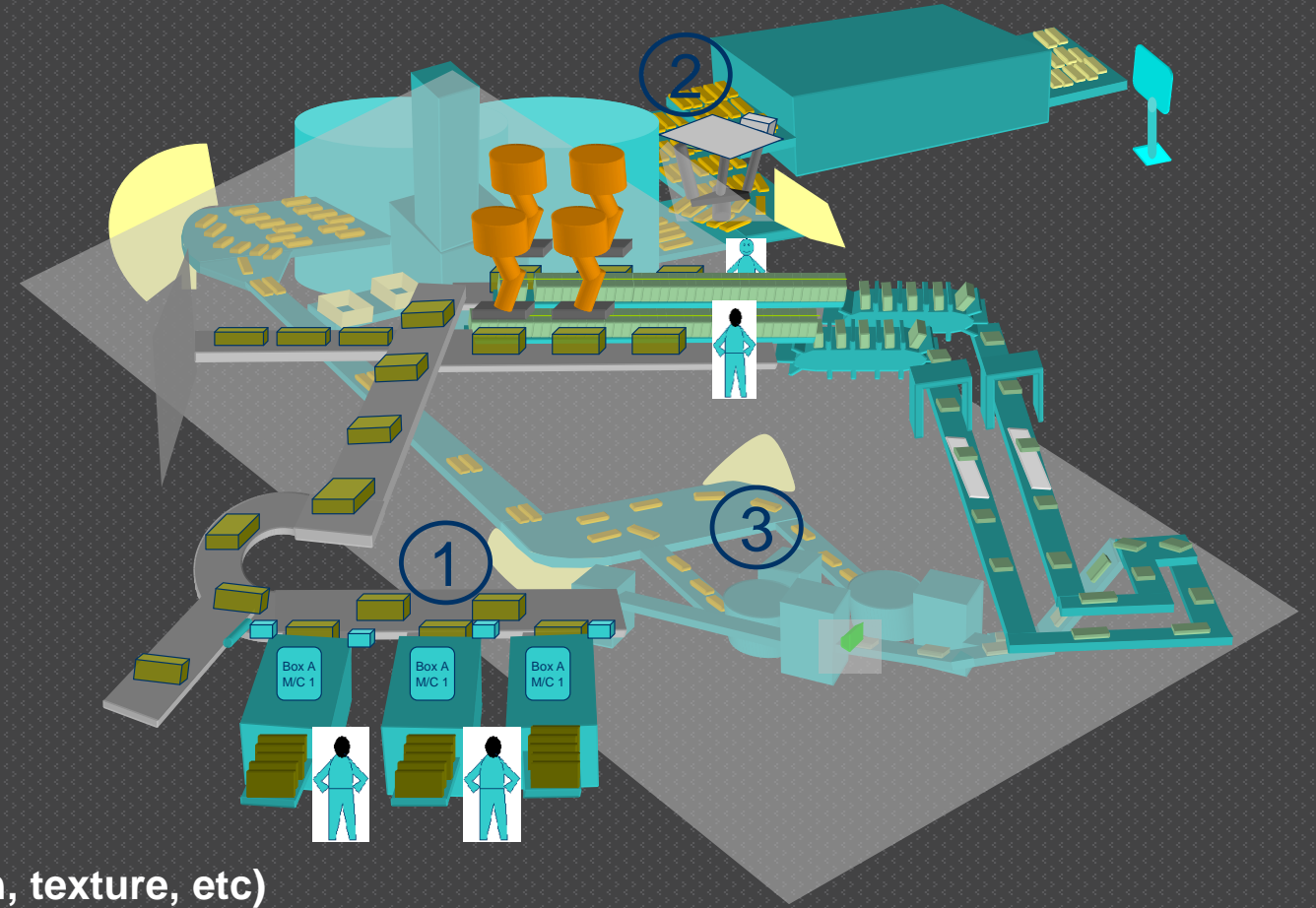
- a) Box forming
- b) Label printing
- c) Box bar code check
- d) Pack bar code/date check
- e) Collating
- f) Case loading
- g) Lid closing and top sealing
- h) bar code check and box count pre SBD

## 2. Quality

- a) Pre- oven product data entry
- b) Pre- chill quality checks (colour, pattern, texture, etc)
- c) Pre flow-wrap weight check

## 3. Handling

- a) Product alignment post chill
- b) Twin pack tray denesting
- c) Product alignment for twin packing
- d) Product handling for twin pack or flow-wrap feed
- e) Product buffering
- f) Promotion labelling



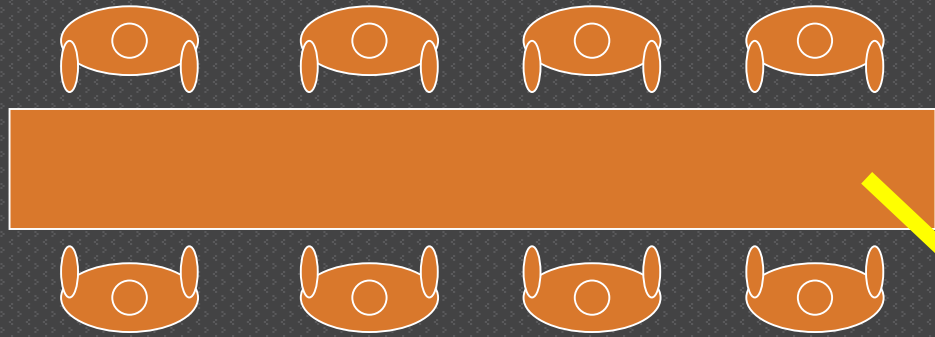
Lines 1, 2 and 3 November 12, 2003





# End of line





**+Utilisation (5% of £225m) = ~£11m**

Saving 7 people on 4 Shifts = 28 people



# End of Line



# RoboBurger™



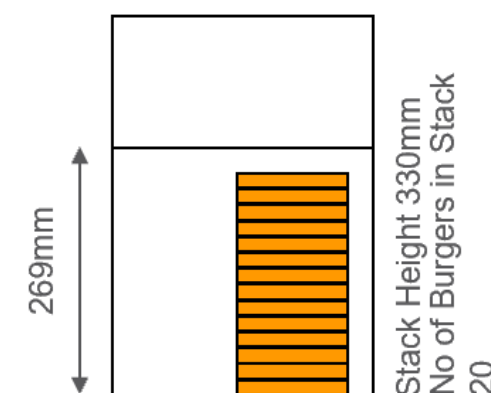
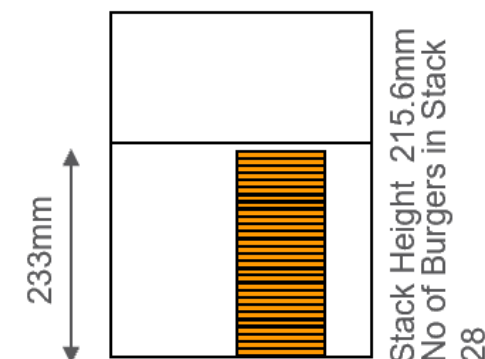
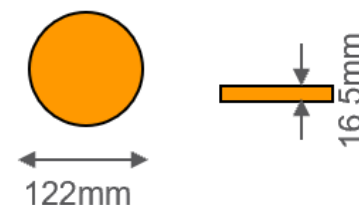
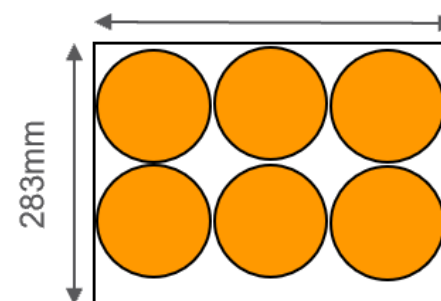
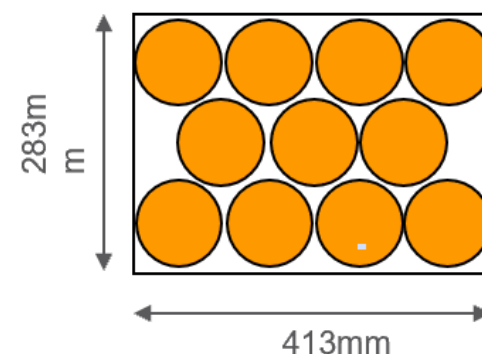
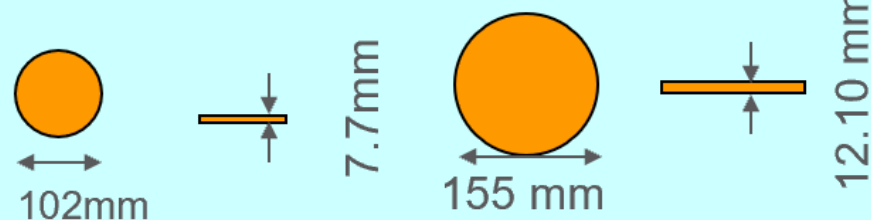


## RoboBurger - Burger and Box Packing Specifications

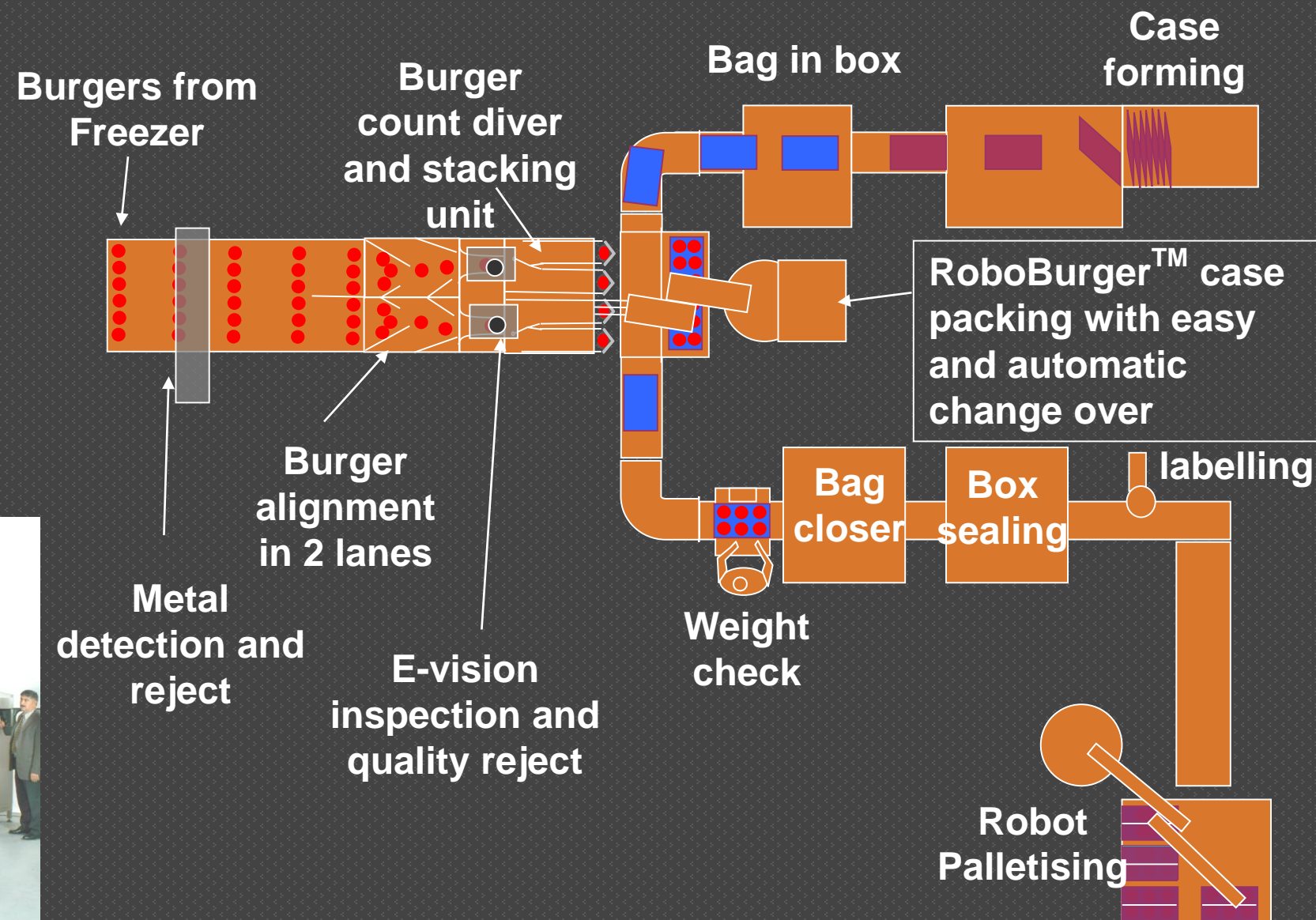
Product Type	McD Hamburger		
Burger size (spec.)	Size	Thickness	Weight
<b>Burger size (max.)</b>	<b>102</b>	<b>7.7</b>	
Packing Layout	No / stack	No of Stacks	No / Box
	27/28	11	298-304
Case (Internal)	Length	Width	Height
Case (External)	413	283	233
Case weight	13.5 kg		
<b>Robot – no of stacks</b>	<b>11</b>		
<b>Robot – no per stack</b>	<b>28</b>		

Product Type	McD Qtr Pounder		
Burger size (spec.)	Size	Thickness	Weight
<b>Burger size (max)</b>	<b>122</b>	<b>16.5</b>	
Packing Layout	No / stack	No of Stacks	No / Box
	15+30extra	6	118-120
Case (Internal)	Length	Width	Height
Case (External)	393	283	269
Case weight	13.5 kg		
<b>Robot – no of stacks</b>	<b>6</b>		
<b>Robot – no per stack</b>	<b>20</b>		

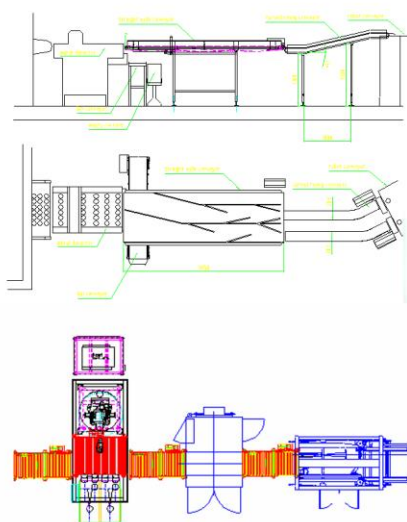
### Range



# RoboBurger™

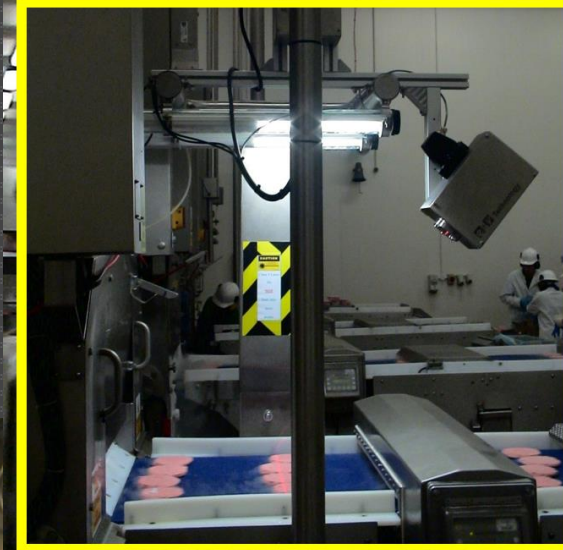


Patent PCT GB02 01376





# Vision Inspection of Burgers





# RoboBurger™



Burgers  
delivered from  
the freezer





# Automation vs Employment



## Patterns of absence

- Average rates of absence across Europe are between 3% and 6% of working time.

- Es **20,000 robots per year may be installed with**
- Er **this money, but this would deal with only the**
- co **absenteeism in Norway.**
- Sp
- in

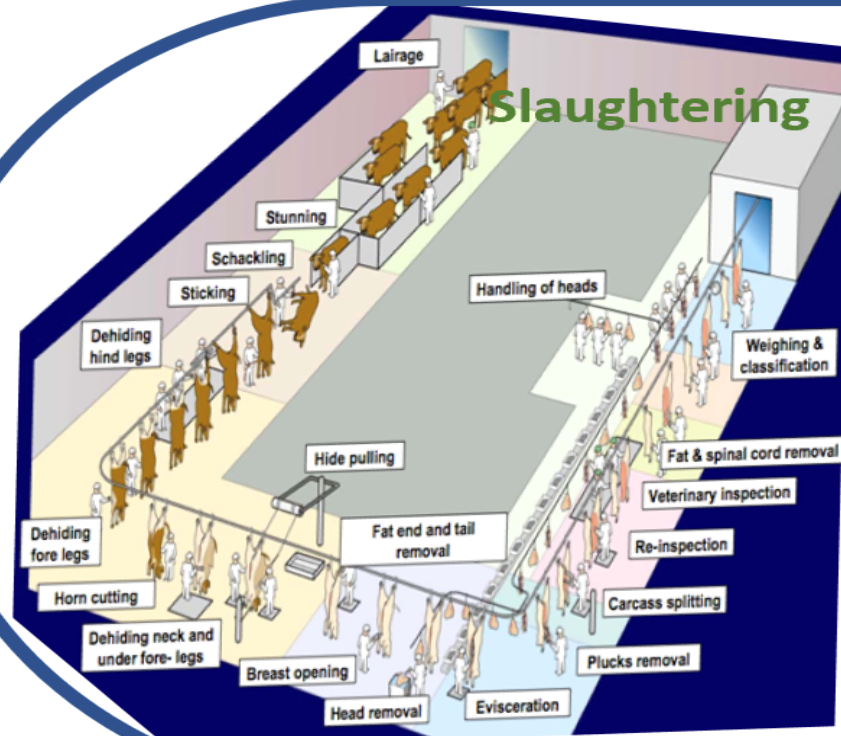
**The installation work to install 20,000 robots would take over 10 years.**

**Assuming we know how to build robots to carry out skilled tasks**

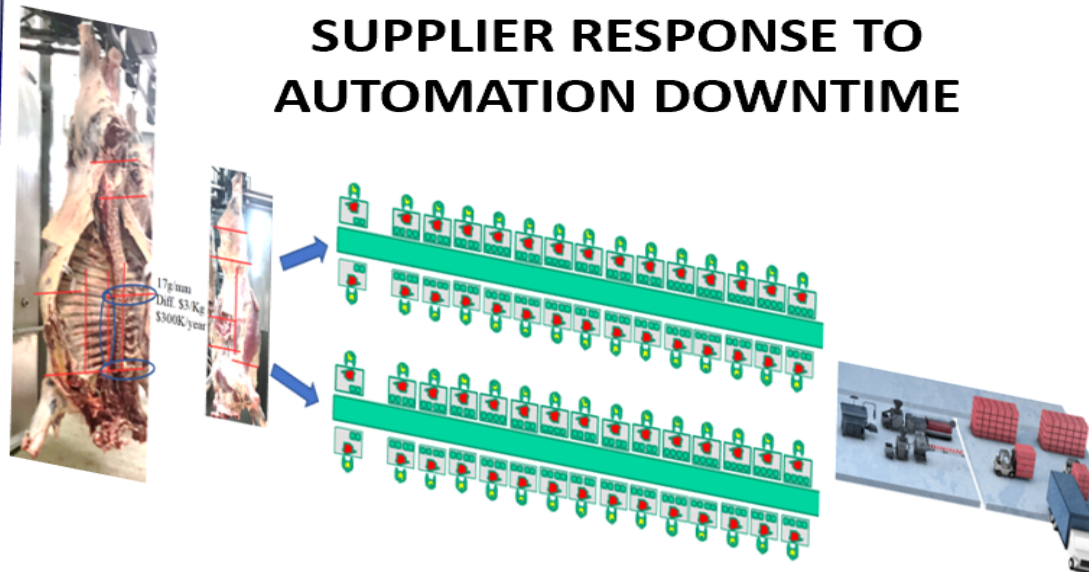
- US

Source: <http://www.investopedia.com/articles/personal-finance/070513/causes-and-costs-absenteeism.asp>

# Managing and delivering



## OPERATIONAL PROCESS AND SUPPLIER RESPONSE TO AUTOMATION DOWNTIME



STOP	PROCUREMENT PROCESS PLAN
Duration	preparation for automation downtime
< 5 min	operators trained to take recovery action
< 8 hours	maintenance staff trained to accomplish recovery
> 8 hours	call out response from suppliers



# Beef operation and management of Change

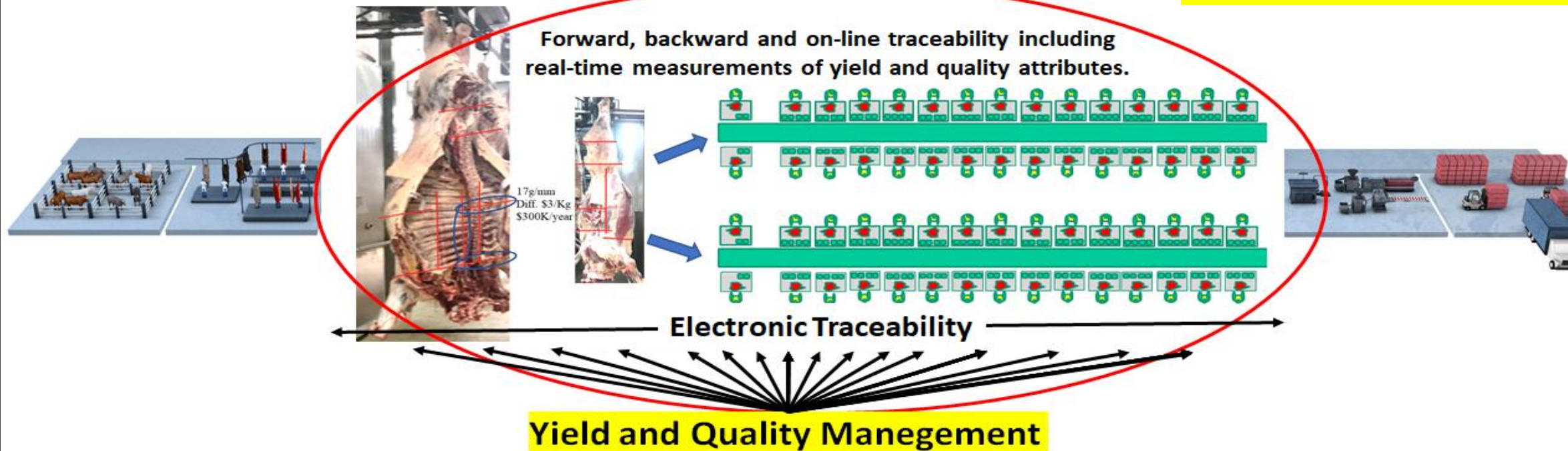


Change management focus: automation  
technology for break up and tracking

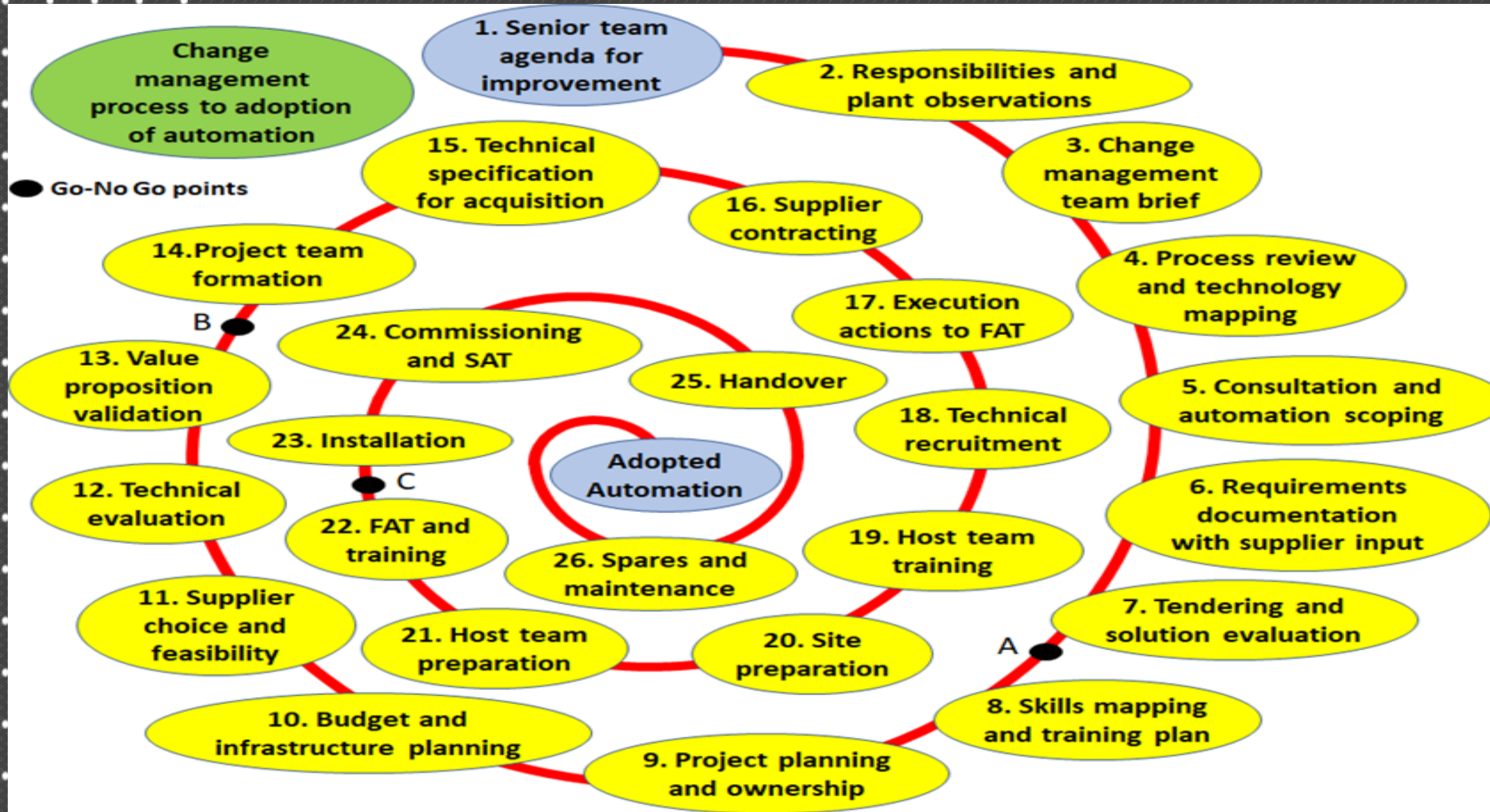


Discipline for transitions in the  
adoption of automation, to  
accomplish sustainable benefits and  
outcomes.

Forward, backward and on-line traceability including  
real-time measurements of yield and quality attributes.



# Change Management & Procurement





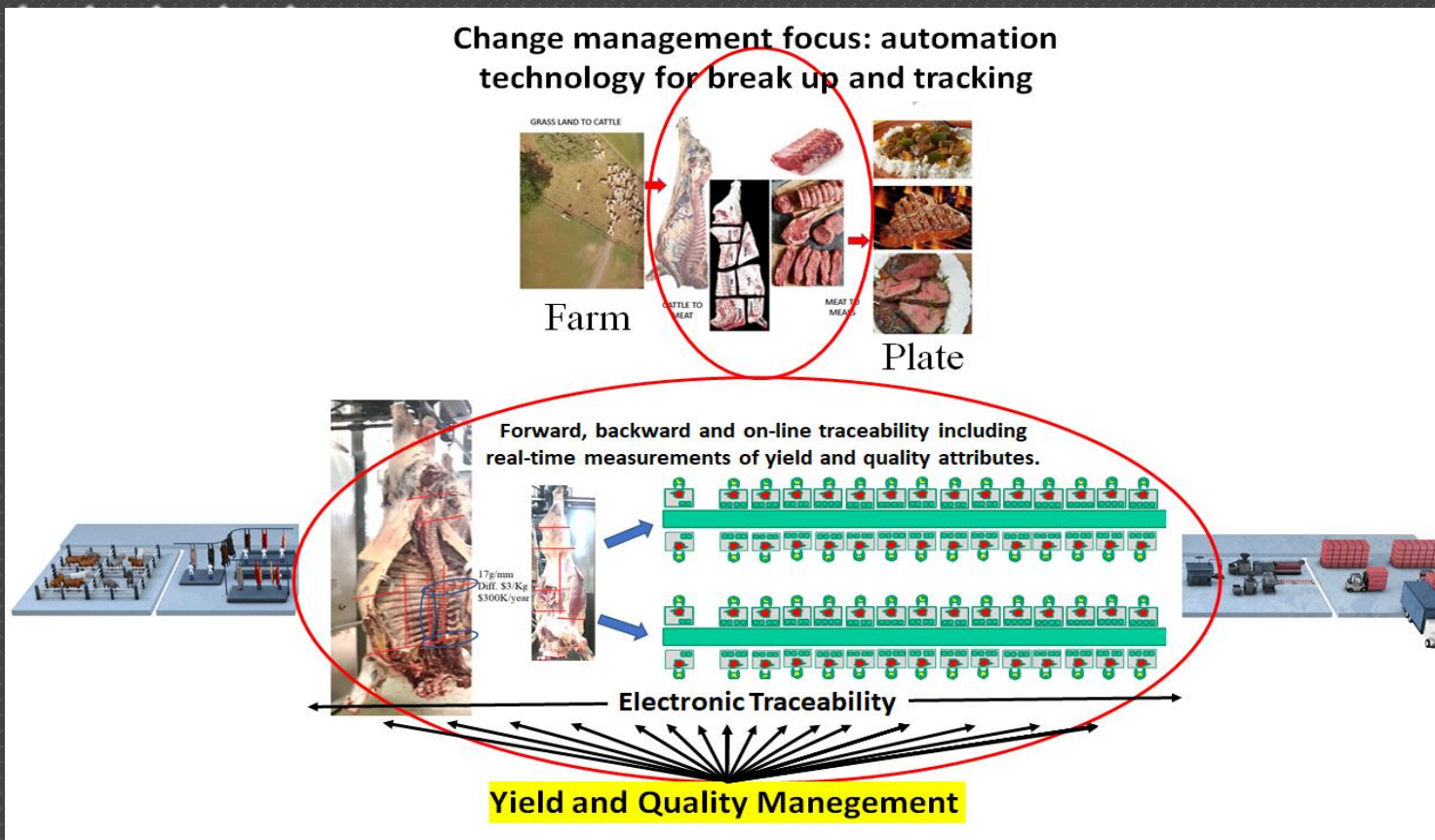
# Change Management



Discipline for transitions in the adoption of automation, to accomplish sustainable benefits and outcomes.

## Important considerations

- Scope and benchmarking
- Change process requirements
- Skills requirements
- Resource requirements
- Infrastructure changes: space, training, etc.
- Mapping needs to supply capability
- Change management capacity



**Koorosh Khodabandehloo (KK)**

**Business and Manufacturing Consultancy**

Adjunct Professor, University of Southern Queensland

**bmcdevon@aol.com**

**Established  
1997**

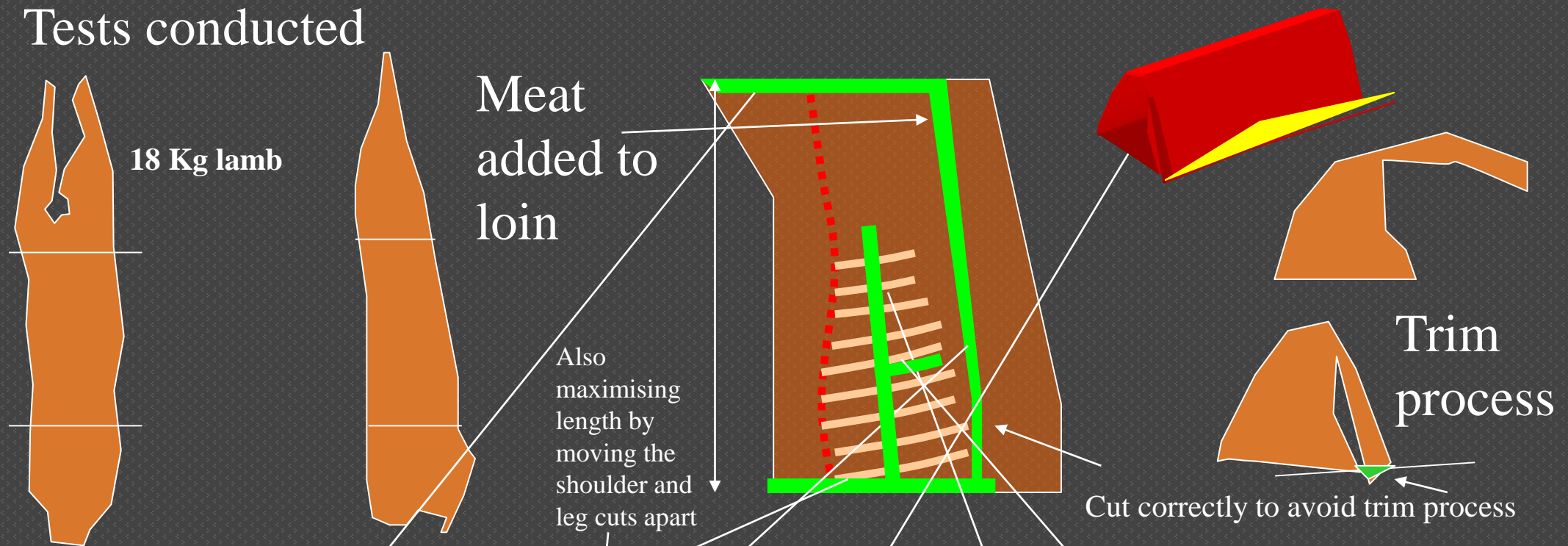


*Thank you*

International Food Automation  
Networking Conference

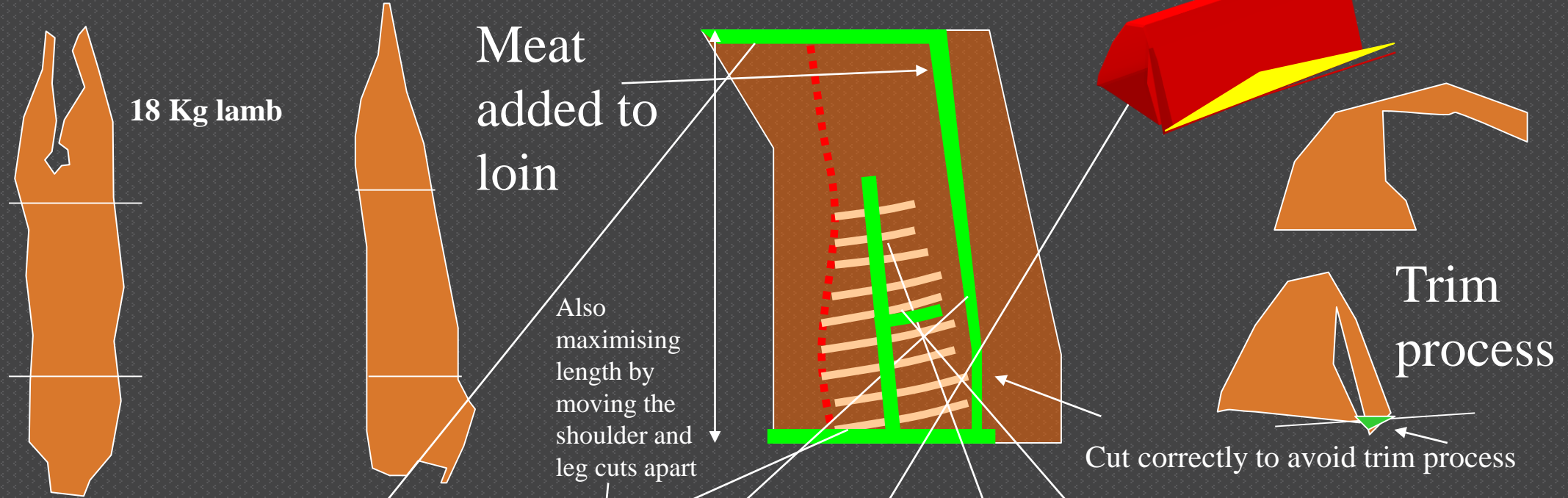


# Tests conducted



Saving calculation against 5mm shift in cut				and optimising yield on rib tip cuts			9th Oct 2001
18 Kg carcass Measured							
	A	B	C	D	E	F	
Gain	Leg-Loin	Shoulder-Loin	Brst - Loin	Trim-Loin	Rib Tip - Loin	Meat btwn Ribs	
£diff	=loin-leg	=loin-shoulder	=loin-Breast	=lion-Trim	=loin-breast	=loin-waste	
gs/5mm/half	30	40	30	15	50	30	
Lambs/year	731000	731000	731000	731000	731000	731000	
Kg/year/lamb	43860	58480	43860	21930	73100	43860	
DIFF £	1.75	3.71	4.76	4.18	4.76	6.19	
£/year	76,755	216,961	104,387	91,667	347,956	271,493	
		5 mm extra	Extra Chop	Total Saving		Leg	4.44
Prim. Cutting	A+B+C	385,383	488,162	873,545		Shoulder	2.48
Rib tip Cut	3*C+E+D	765,503		765,503		Chops	6.19
Meat btwn ribs	F	271,493		271,493		Breast	1.43
						Trim	2.01
						Waste	-
Total saving per year from this approach				1,910,542			

# Tests conducted



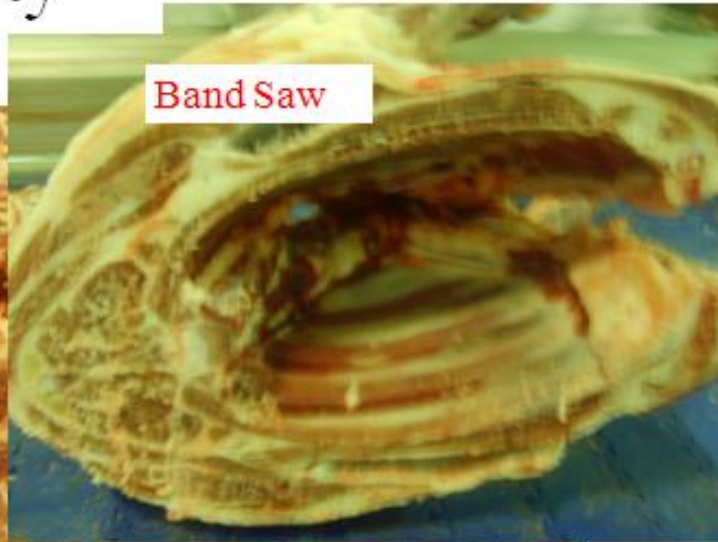
Saving calculation against 5mm shift in cut				and optimising yield on rib tip cuts			16-Jan-02
18 Kg carcass Measured							
	A	B	C	D	E	F	
Gain	Leg-Loin	Shoulder-Loin	Brst - Loin	Trim-Loin	Rib Tip - Loin	Meat btwn Ribs	
£diff	=loin-leg	=loin-shoulder	=loin-Breast	=lion-Trim	=loin-breast	=loin-waste	
gs/5mm/half	30	40	30	15	50	30	
Lambs/year	731000	731000	731000	731000	731000	731000	
Kg/year/lamb	43860	58480	43860	21930	73100	43860	
DIFF £	- 0.17	1.79	2.84	3.42	4.27	4.27	
£/year	- 7,456	104,679	124,562	75,001	312,137	187,282	
		5 mm extra	Extra Chop	Total Saving		Leg	4.44
Prim. Cutting	A+B+C	172,224	235,528	407,752		Shoulder	2.48
Rib tip Cut	3*C+E+D	760,825		760,825		Chops	4.27
Meat btwn ribs	F	187,282		187,282		Breast	1.43
						Trim	0.85
						Waste	-
Total saving per year from this approach				1,355,859			



# Cut quality



Band Saw



Knife Blade



# Primal cut layout

